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UTILITY PATENT APPLICATION TRANSMITTAL

(Only for new nonprovisional applications under 37 CFR 1.53(b))

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APPLICATION ELEMENTS

See MPEP chapter 600 concerning utility patent application contents.

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[Note Box 5 below]

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Signed Statement attached deleting inventor(s)
named in the prior application, see 37 CFR
1.63(d)(2) and 1.33(b).

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The entire disclosure of the prior application, from which a copy of the
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8. ☐ Assignment Papers (cover sheet & document(s))

9. ☐ 37 CFR 3.73(b) Statement ☐ Power of Attorney
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10. ☐ English Translation Document (if applicable)

11. ☐ Information Disclosure Statement (IDS)/PTO-1449 ☐ Copies of IDS
Citations

12. ☐ Preliminary Amendment

13. ☒ Return Receipt Postcard (MPEP 503)
(Should be specifically itemized)

14. ☐ Small Entity Statement(s) ☐ Statement filed in prior application
Status still proper and desired

15. ☐ Certified Copy of Priority Document(s)
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CLAIMS	(1) FOR	(2) NUMBER FILED	(3) NUMBER EXTRA	(4) RATE	(5) CALCULATIONS
	TOTAL CLAIMS (37 CFR 1.16(c))	24-20 =	4	X \$ 18.00 =	\$72.00
	INDEPENDENT CLAIMS (37 cfr 1.16(b))	15-3 =	12	X \$ 78.00 =	\$936.00
	MULTIPLE DEPENDENT CLAIMS (if applicable) (37 CFR 1.16(d))			\$260.00 =	\$
				BASIC FEE (37 CFR 1.16(a))	\$760.00
	Total of above Calculations =				\$1768.00
	Reduction by 50% for filing by small entity (Note 37 CFR 1.9, 1.27, 1.28).				
	TOTAL =				\$1768.00

19. Small entity status

- a. ☐ A Small entity statement is enclosed
- b. ☐ A small entity statement was filed in the prior nonprovisional application and such status is still proper and desired.
- c. ☐ Is no longer claimed.

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- a. ☒ Fees required under 37 CFR 1.16.
- b. ☒ Fees required under 37 CFR 1.17.
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SIGNATURE OF APPLICANT, ATTORNEY, OR AGENT REQUIRED

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DATE	July 26, 1999

DATA COMMUNICATION SYSTEM, DATA COMMUNICATION CONTROL
METHOD AND ELECTRONIC APPARATUS

BACKGROUND OF THE INVENTION

5 Field of the Invention

The present invention relates to a data
communication system, a data communication control
method and an electronic apparatus, particularly to a
network in which digitized image signals are dealt
10 with.

Related Background Art

Recently, techniques for transmitting digitized
animated image signals in real time have been
developed. As one of the techniques, there is a high-
15 rate serial bus (hereinafter referred to as 1394 serial
bus) in conformity with IEEE (the Institute of
Electrical and Electronics Engineers, Inc.) 1394-1995
standards (hereinafter referred to as IEEE 1394
standards). The technique is noted as a communication
20 interface of a camera incorporating type digital video
recorder (hereinafter referred to as DVCR) or another
AV (Audio/Visual) apparatus.

In the IEEE 1394 standards, however, physical,
electrical constitution of a connector, two types of
25 most basic data transfer systems, and the like are
merely defined, and it is not defined what type of
apparatus is used and how the apparatus is constructed

to be remote-controlled. Moreover, a type of data to be transmitted, a data format and a communication procedure for the transmittance are also indefinite.

Therefore, in the 1394 serial bus, a camera unit equipped in DVCR cannot be remote-operated, so that a user must directly operate a DVCR unit.

Furthermore, in the 1394 serial bus, a high-rate image transfer can be performed, but the setting of an image quality for a displayed image of a certain apparatus, or the setting of an image quality for a taken image of a certain apparatus cannot be remote-operated.

On the other hand, in the conventional DVCR, auto-focusing or another specific function is only preset for a fixed area on the taken image. Therefore, the user himself cannot set an arbitrary area for the taken image, or cannot select or set a desired function for the area. Furthermore, such operation cannot be performed in a remote manner.

SUMMARY OF THE INVENTION

An object of the present invention is to solve the above-described problems.

Another object of the invention is to provide an operation environment to realize various controls and inquiries concerning a taken image of an image pickup unit and a displayed image of a display unit by remote

operation in a data communication system, data communication control method and electronic apparatus.

As a preferred embodiment for such objects, in the present invention there is disclosed a data

5 communication system, comprising: a target having an image pickup unit; a controller for remote-operating the image pickup unit; a data line for connecting the target and the controller, the data line supporting a first communication mode and a second communication
10 mode; and a control command for setting a predetermined area in an image outputted by the image pickup unit, wherein the target uses the first communication mode to transmit the image, and the controller uses the second communication mode to transmit the control command.

15 Moreover, as another embodiment, in the present invention there is disclosed a data communication control method, comprising the steps of: transmitting, by a target, an image outputted by an image pickup unit using a first communication mode supported by a data
20 line; and transmitting, by a controller, a control command for setting a predetermined area in the image to the target using a second communication mode supported by the data line, the controller remote-operating the image pickup unit.

25 Furthermore, as another embodiment, in the present invention there is disclosed an electronic apparatus, comprising: an image pickup unit for outputting an

image; and communication means for communicating with a controller connected to a data line, the controller remote-operating the image pickup unit, the data line supporting a first communication mode and a second communication mode, wherein the communication means uses the first communication mode to transmit the image, and uses the second communication mode to receive a control command from the controller, and the image pickup unit sets a predetermined area in the image based on the control command.

Additionally, as another embodiment, in the present invention there is disclosed a data communication control method, comprising the steps of: using a first communication mode supported by a data line to transmit an image from an image pickup unit; and using a second communication mode supported by the data line to receive a control command for setting a predetermined area in the image, the control command being transmitted by a controller for remote-operating the image pickup unit.

Moreover, as another embodiment, in the present invention there is disclosed an electronic apparatus, comprising: means for remote-operating an image pickup unit of a target connected to a data line, the data line supporting a first communication mode and a second communication mode; and communication means for transmitting a control command for setting a

predetermined area in an image outputted by the image pickup unit, the image being transmitted using the first communication mode, wherein the communication means uses the second communication mode to transmit the control command.

Furthermore, as another embodiment, in the present invention there is disclosed a data communication system, comprising: a target having a display unit; a controller for remote-operating the display unit; a data line for connecting the target and the controller, the data line supporting a first communication mode and a second communication mode; and a control command for regulating an image displayed by the display unit, wherein the target uses the first communication mode to receive the image, and the controller uses the second communication mode to transmit the control command.

Additionally, as another embodiment, in the present invention there is disclosed a data communication control method, comprising the steps of: receiving, by a target, an image displayed by a display unit using a first communication mode supported by a data line; and transmitting, by a controller, a control command for regulating the image to the target using a second communication mode supported by the data line, the controller remote-operating the display unit.

Moreover, as another embodiment, in the present invention there is disclosed an electronic apparatus,

comprising: a display unit for displaying an image; and communication means for communicating with a controller connected to a data line, the controller remote-operating the display unit, the data line supporting a first communication mode and a second communication mode, wherein the communication means uses the first communication mode to receive the image, and uses the second communication mode to receive a control command from the controller, and the display unit regulates the image based on the control command.

Furthermore, as another embodiment, in the present invention there is disclosed a data communication control method, comprising the steps of: receiving an image displayed by a display unit using a first communication mode supported by a data line; and receiving a control command for regulating the image using a second communication mode supported by the data line, the control command being transmitted by a controller for remote-operating the display unit.

Additionally, as another embodiment, in the present invention there is disclosed an electronic apparatus, comprising: means for remote-operating a display unit of a target connected to a data line, the data line supporting a first communication mode and a second communication mode; and communication means for transmitting a control command for regulating an image displayed by the display unit, the image being

transmitted using the first communication mode, wherein the communication means uses the second communication mode to transmit the control command.

Moreover, as another embodiment, in the present invention there is disclosed a data communication system, comprising: a target having an image pickup unit; a controller for remote-operating the image pickup unit; a data line for connecting the target and the controller, the data line supporting a first communication mode and a second communication mode; and a control command for regulating an image outputted by the image pickup unit, wherein the target uses the first communication mode to transmit the image, and the controller uses the second communication mode to transmit the control command.

Furthermore, as another embodiment, in the present invention there is disclosed a data communication control method, comprising the steps of: transmitting, by a target, an image outputted by an image pickup unit using a first communication mode supported by a data line; and transmitting, by a controller, a control command for regulating the image using a second communication mode supported by the data line, the controller remote-operating the image pickup unit.

Additionally, as another embodiment, in the present invention there is disclosed an electronic apparatus, comprising: an image pickup unit for

outputting an image; and communication means for communicating with a controller connected to a data line, the controller remote-operating the image pickup unit, the data line supporting a first communication mode and a second communication mode, wherein the communication means uses the first communication mode to transmit the image, and uses the second communication mode to receive a control command from the controller, and the image pickup unit regulates the image based on the control command.

Moreover, as another embodiment, in the present invention there is disclosed a data communication control method, comprising the steps of: transmitting an image outputted by an image pickup unit using a first communication mode supported by a data line; and receiving a control command for regulating the image using a second communication mode supported by the data line, the control command being transmitted by a controller for remote-operating the image pickup unit.

Furthermore, as another embodiment, in the present invention there is disclosed an electronic apparatus, comprising: means for remote-operating an image pickup unit of a target connected to a data line, the data line supporting a first communication mode and a second communication mode; and communication means for transmitting a control command for regulating an image outputted by the image pickup unit, the image being

transmitted using the first communication mode, wherein the communication means uses the second communication mode to transmit the control command.

Still other objects of the present invention, and the advantages thereof, will become fully apparent from the following detailed description of the embodiments.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a block diagram showing a constitution of a data communication system of a first embodiment.

Fig. 2 is a view showing one example of a graphical user interface of the first embodiment.

Figs. 3A, 3B and 3C are views showing types of commands (control command, status command, notify command).

Fig. 4 is an explanatory view of a communication procedure based on FCP.

Figs. 5A and 5B are views showing data formats of CTS commands of the first embodiment.

Fig. 6 is a view showing the data format of FRAME COMMAND of the first embodiment.

Figs. 7A and 7B are views showing data formats of CTS responses of the first embodiment.

Fig. 8 is a view showing a procedure for inquiring the number of frames.

Fig. 9 is a view showing CTS command for inquiring the number of frames.

Fig. 10 is a view showing CTS response for the inquiry of the number of frames.

Fig. 11 is a view showing a procedure for setting various frames.

5 Fig. 12 is a view showing CTS command for setting a rectangular frame.

Fig. 13 is a view showing CTS command for setting a circular frame.

10 Fig. 14 is a view showing CTS command for setting a polygonal frame.

Fig. 15 is a view showing CTS command for setting a pixel frame.

Fig. 16 is a view showing a procedure for inquiring a frame area.

15 Fig. 17 is a view showing CTS command for inquiring the frame area.

Fig. 18 is a view showing a procedure for instructing displaying/not-displaying of a selected frame.

20 Fig. 19 is a view showing CTS command for instructing the displaying/not-displaying of the selected frame.

Fig. 20 is a view showing a procedure for controlling a function of the selected frame.

25 Fig. 21 is a view showing CTS command for controlling the function of the selected frame.

Fig. 22 is a view showing one example of a

function which can be controlled by CTS command.

Fig. 23 is a view showing a procedure for inquiring a function of the selected frame.

Fig. 24 is a view showing CTS command for inquiring the function of the selected frame.

Fig. 25 which is comprised of Fig. 25A and 25B are block diagrams showing a constitution of a data communication system of a second embodiment.

Fig. 26 is a view showing a packet format of Asynchronous packet.

Figs. 27A and 27B are views showing data formats of CTS command and CTS response of the second embodiment.

Fig. 28 is a view showing a data format of INPUT SIGNAL MODE CONTROL COMMAND of the second embodiment.

Fig. 29 is a view showing one example of a graphical user interface of the second embodiment.

Fig. 30 is a view showing a procedure for remote-controlling a displayed image.

Fig. 31 is a view showing a procedure for remote-controlling a taken image.

Fig. 32 is a view showing a communication method for transferring moving image data and a communication method for transferring CTS command, in the embodiment.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The preferred embodiments of the present invention

will now be described in detail hereinafter with reference to the accompanying drawings.

(First Embodiment)

In a first embodiment, an operation environment will be described in which a network for realizing a real-time data communication of IEEE 1394 serial bus or the like is connected to a target having a camera unit and a controller for remote-operating the target, and a taken image of the camera unit is remote-operated while a controller display screen is being observed.

Fig. 1 is a block diagram showing a constitution of a data communication system of the first embodiment.

In Fig. 1, a camera incorporating type digital video recorder (hereinafter referred to as DVCR) 10 is a target of the present embodiment, and a personal computer (hereinafter referred to as PC) 20 is a controller of the embodiment. Numeral 30 denotes a communication cable in conformity with IEEE 1394 standards. Here, each of DVCR 10 and PC 20 is provided with a digital interface (hereinafter referred to as 1394 interface) 40 in conformity with IEEE 1394 standards. When apparatuses are interconnected using the communication cable 30, a bus type network is constituted to realize a high-rate serial data communication.

The DVCR 10 of Fig. 1 is provided with a camera sub-unit 11 for generating an image signal of a

predetermined format from an optical image of a subject. An animated image taken by the camera sub-unit 11 of DVCR 10 is transferred in real time using Isochronous transfer system based on IEEE 1394

standards. Moreover, a control command asynchronously transferred between DVCR 10 and PC 20 is transferred using Asynchronous transfer system based on IEEE 1394 standards.

Here, Isochronous transfer system is a communication system which assures the transfer of a constant amount of data for each predetermined communication cycle (one communication cycle is nearly 125 μ s) and which is suitable for a real-time communication of animated images, voices and the like as shown in 3202 and 3203 of Fig. 32. Also, Isochronous transfer system is a broadcast communication which does not specify communication destinations. Each device manages Isochronous data outputted by using channel number (chA, chB shown in Fig. 31) assigned to the device and a communication band. Moreover, Asynchronous transfer system is a communication system which becomes effective when the control command, file data and the like are asynchronously transferred as required as shown in 3204 and 3206 of Fig. 32. Further, there are a one-on-one communication specifying the communication destination and the broadcast communication not specifying the

communication destination in Asynchronous transfer system. Though a receiving node returns acknowledgment (ack 3150, 3107 in Fig. 31) in the one-on-one communication, the receiving node does not return the acknowledgment in the broadcast communication. CTS command and CTS response described later use the one-on-one communication. Here, Isochronous transfer system and Asynchronous transfer system can be mixed in a time division manner, and in one communication cycle period, Isochronous transfer system has a higher priority than Asynchronous transfer system because an idle term (Isochronous gap in Fig. 31) in which the Isochronous transfer system is executed is set shorter than an idle term (Subaction gap in Fig. 31) in which the Asynchronous transfer system is executed. Accordingly, the Isochronous transfer system is executed subsequent to CSP (Cycle Start Packet) 3101 transferred initially in each communication cycle, prior to the Asynchronous transfer system. By the function, animated images, voices and other information signals having real-time properties can be transmitted without being interrupted in the data communication system of the embodiment.

As described above, in the embodiment, since the devices are interconnected via the 1394 interface, communication data of each device can be communicated serially and bidirectionally. Therefore, as compared

with the conventional parallel communication, the cost of the entire system can be reduced, and a higher-rate communication can be realized.

In the PC 20 of Fig. 1, numeral 21 denotes a control unit, 22 denotes a monitor, 23 denotes an operation unit constituted of a mouse, keyboard and the like, and 24 denotes a hard disc or another storage medium. In the storage medium 24, an application for controlling the camera sub-unit 11 the target has is stored as a program code. The control unit 21 reads the program code from the storage medium 24, and starts the application to control a display screen of the monitor 22 and the communication with DVCR 10 in accordance with the operation of the operation unit 23.

Fig. 2 is a view showing one example of the display screen of the monitor 22 provided in the PC 20. Additionally, the display screen of the monitor 22 is prepared based on the application processed by the control unit 21.

In Fig. 2, numeral 201 denotes a preview screen on which a taken image isochronously transferred from the DVCR 10 is displayed in an animated manner.

Moreover, in Fig. 2, numeral 202 denotes Wide button for moving a digital zoom of DVCR 10 in a wide direction, 203 denotes Tele button for moving the digital zoom of DVCR 10 in a tele-direction, 204 denotes Near button for moving a focus of DVCR 10 in a

near direction, 205 denotes Far button for moving the focus of DVCR 10 in a far direction, and 206 denotes a control button for setting an area (hereinafter referred to as the frame) having various shapes on the taken image of the DVCR 10. The buttons 202 to 206 are indicated with icons on the screen.

Furthermore, in Fig. 2, numeral 2061 denotes a control button for selecting a desired frame from frames which have been set, 2062 denotes a control button for setting a frame having a rectangular shape (hereinafter referred to as the rectangular frame) on the screen of the taken image, 2063 denotes a control button for setting a frame having a circular shape (hereinafter referred to as the circular frame), 2064 denotes a control button for setting a frame having a polygonal shape (hereinafter referred to as the polygonal frame), and 2065 denotes a control button for setting a pixel unit frame (hereinafter referred to as the pixel frame).

Additionally, in Fig. 2, numerals 207 to 210 are frames which are set on the taken image screen using the control button 206, and 211 denotes a menu window for performing the setting, or inquiring of various functions for the selected frame.

In Fig. 2, when the buttons 202 to 205 are operated by the user, the PC 20 asynchronously transfers to the DVCR 10 a control command

corresponding to an operation result. The camera sub-unit 11 of DVCR 10 controls its operation in accordance with a content of the received control command. Fig. 3A shows one example of a control command for controlling the camera sub-unit 11.

For example, when the buttons 202, 203 are operated, PC 20 asynchronously transfers to the DVCR 10 a control command "ZOOM" to control a digital zoom of the camera sub-unit 11. The DVCR 10 operates the digital zoom of the camera sub-unit 11 in the wide direction or the tele-direction in accordance with the content of the control command.

Moreover, in order to know a state of the camera sub-unit 11 of DVCR 10, PC 20 can asynchronously transfer a status command shown in Fig. 3B. The PC 20 can know the current state of the camera sub-unit 11 by a response to the status command.

For example, when the PC 20 asynchronously transfers the status command "ZOOM" to the DVCR 10, the DVCR 10 responds to the PC 20 by transmitting position information of the digital zoom of the camera sub-unit 11.

Furthermore, the PC 20 can asynchronously transfer a notify command shown in Fig. 3C to the DVCR 10. When a change occurs in the state designated by the notify command, the camera sub-unit 11 having received the notify command returns the state change to the PC 20.

For example, the PC 20 asynchronously transfers to the DVCR 10 a notify command "ZOOM" to designate a position of digital zoom of the camera sub-unit 11. In this case, when the digital zoom of the camera sub-unit 11 reaches the position, the DVCR 10 returns a response.

In the embodiment, various commands (control command, status command, notify command) shown in Fig. 3 are transmitted by FCP (Function Control Protocol). Fig. 4 is an explanatory view of a communication procedure of FCP. In the embodiment, a series of communication procedure shown in Fig. 4 is hereinafter referred to as a command transaction, and a combination of a command transmitted based on the command transaction and a response to the command is referred to as CTS (Command Transaction Set) command and CTS response.

In Fig. 4, first, the PC 20 (controller) uses Asynchronous Write transaction based on IEEE 1394 standards to write CTS command 401 into a predetermined memory space (command register) provided in the DVCR 10 (target). The target returns an acknowledgment 402 for the Asynchronous transfer to the controller.

Subsequently, the target executes a processing corresponding to the CTS command 401, and additionally prepares CTS response 403 from an execution result. Thereafter, the target uses Asynchronous Write

transaction to write the CTS response 403 into a predetermined memory space (response register) provided in the controller. The controller returns an acknowledgment 404 for the Asynchronous transfer to the target.

A packet format of Asynchronous packet for transmitting the CTS command and CTS response of the embodiment will next be described with reference to Fig. 26. The packet is transferred to another node by "write transaction" as one of services provided by Asynchronous transfer. The "write transaction" is a service for designating a predetermined area on CSR (Control and Status Register) space of a certain node to write desired data into the area. Here, the CSR space is an address space of 64 bits in conformity with IEEE 1212 standards. Upper 16 bits of the CSR space are used in designation of bus and node (bus ID and node ID), while lower 48 bits are used as an address space of each node.

In Fig. 26, numeral 2600 denotes Destination_ID field, 2602 denotes a transaction label (hereinafter referred to as tl) field, 2604 denotes a retry code (hereinafter referred to as Rt) field, and 2606 denotes a transaction code (hereinafter referred to as tcode) field.

Numerals 2608 and 2610 denote a priority (hereinafter referred to as Pri) field and a source ID

(hereinafter referred to as Source_ID) field, 2612 denotes Destination_offset field, 2614 denotes Data_length field, 2616 denotes an extended transaction code (hereinafter referred to as Extended_tcode) field, 2618 denotes a header CRC (hereinafter referred to as Header_CRC) field, 2620 denotes a data field, and 2622 denotes a data CRC (hereinafter referred to as Data_CRC) field.

The Asynchronous packet of Fig. 26 is a data packet having a unit of four bytes (32 bits, hereinafter referred to as quadred). The Destination_ID field 2600 (16 bits) indicates a node ID to designate a destination on the same bus. In the next 6-bit field, the transaction label (tl) field 2602 (6 bits) indicates a tag peculiar to each transaction. In the next 2-bit field, the retry (Rt) code 2604 (2 bits) designates whether the packet makes a retry.

The transaction code (tcode) 2606 (4 bits) designates a packet format, and a transaction type to be executed. In the embodiment, for example, the value is "0001₂", requesting for a writing transaction of a data block. The priority (Pri) field 2608 (4 bits) designates a priority. In the embodiment, since the asynchronously transferred packet is used, the value of the field is "0000₂".

The Source_ID field 2610 (16 bits) indicates a node ID to designate a transmission end on the same

bus. The Destination_offset field 2612 (48 bits) designates lower 48 bits on the CSR space of the destination node.

The Data_length field 2614 (16 bits) indicates a length of a data field described later in the unit of byte. In the embodiment the Extended_tcode field 2616 (16 bits) is "0000₁₆".

The above-described Destination_ID field 2600 to the Extended_tcode field 2616 are referred to as a packet header. The Header_CRC field 2618 (32 bits) is used in error detection of the packet header.

In the data field 2620 (variable length), CTS command frame and CTS response frame described later are set. The data field 2620 is referred to as the payload. When the data field 2620 is less than a multiple of quadred, "0" is filled.

The Data_CRC field 2622 (32 bits) is used in the error detection of the data field 2620 in the same manner as the Header_CRC field 2618.

Data formats of CTS command transferred to the target from the controller and CTS response transferred to the controller from the target will be described in detail hereinafter with reference to Figs. 5 to 7.

Fig. 5A is a view showing the data format of CTS command asynchronously transferred to the target from the controller.

In Fig. 5A, numeral 504 denotes CTS command. In a

ctype field of the CTS command 504, codes for designating command types are stored. Fig. 5B shows examples of the command types stored in the ctype field.

5 Moreover, in the CTS command 504, data specifying to which sub-unit provided in the target the command corresponds are stored in Subunit_type field and Subunit ID field. In an opcode field and operand [0] to operand [n] fields, data designating a content of an
10 actual command are stored.

 Fig. 6 is a view showing one example of the data which are stored in the opcode field and the operand [0] to operand [n] fields. In Fig. 6, the setting of a frame for the taken image of the target, or CTS
15 commands for setting various functions concerning the frame will be described.

 In Fig. 6, a code indicating that the command is a command "FRAME" concerning frame control is stored in the opcode field. In the operand [0] field, a code
20 indicating a processing performed by the command is stored. In the operand [1] field, a frame number indicating a frame as an object of the command is stored. In the operand [2] to operand [n] fields, various parameters for use in the command (e.g.,
25 position information of each coordinate to designate a frame range) are stored.

 Fig. 7A is a view showing a data format of CTS

response asynchronously transferred to the controller from the target.

In Fig. 7A, a code designating a response type is stored in a response field. Fig. 7B shows examples of response types stored in the response field.

Moreover, in Fig. 7A, data specifying from which sub-unit provided in the target the response is transferred are stored in Subunit_type field and Subunit ID field. In the opcode field and the operand [0] to operand [n] fields, data designating a content of an actual response are stored.

A procedure will be described hereinafter in which the controller uses the CTS commands shown in Fig. 5 and the CTS responses shown in Fig. 7 to set the frame for the taken image of the target, set various functions for the inquiry or the frame and to remote-operate the inquiry.

(1) Inquiry of the Number of Frames

In the embodiment, the application of PC 20 can inquire of the camera sub-unit 11 about the number of frames which can be set in the taken image of the camera sub-unit 11. A procedure for inquiring the number of frames will be described hereinafter with reference to Fig. 8.

In the PC 20, the user starts the application to display a screen on the monitor 22 as shown in Fig. 2 (801).

After the application is started, the user uses the operation unit 23 to operate the menu window 211, and instructs the inquiry of the number of frames which can be set (802).

5 After the user's instruction input is confirmed, the PC 20 prepares CTS command to inquire the number of frames (803). In this case, the CTS command prepared by the PC 20 is shown in Fig. 9.

10 In Fig. 9, in a ctype field 901 is set "Status" which indicates that the command is a status command to inquire the state of the camera sub-unit 11. Data specifying the camera sub-unit 11 of DVCR 10 are stored in Subunit_type field 902 and Subunit ID field 903.

15 Moreover, in Fig. 9, a code indicating a command "FRAME" concerning the frame control is set in an opcode field 904. In an operand [0] field 905 is set a command "Max Frame" to inquire the maximum number of frames which can be set in the camera sub-unit 11. Dummy data is set in an operand [1] field 906.

20 After the CTS command of Fig. 9 is prepared, the PC 20 sets the CTS command in Asynchronous packet shown in Fig. 26, and transfers the packet to the camera sub-unit 11 (804).

25 After receiving the above-described CTS command, the camera sub-unit 11 returns an acknowledgment to the PC 20 (805).

Moreover, the camera sub-unit 11 executes a

processing corresponding to the received CTS command (806), and additionally prepares CTS response corresponding to the CTS command (807). In this case, the CTS response prepared by the camera sub-unit 11 is shown in Fig. 10.

In Fig. 10, "Stable" is set in a response field 1001. Data specifying the camera sub-unit 11 of DVCR 10 are stored in Subunit_type field 1002 and Subunit ID field 1003.

Moreover, in Fig. 10, the same codes "FRAME" and "Max Frame" as the CTS commands transferred from the PC 20 are set in an opcode field 1004 and operand [0] field 1005. The maximum number of frames which can be set in the camera sub-unit 11 is set in an operand [1] field 1006.

After the CTS responses of Fig. 10 are prepared, the camera sub-unit 11 sets the CTS responses in Asynchronous packet shown in Fig. 26, and transfers the packet to the PC 20 (808).

After receiving the above-described CTS response, the PC 20 returns an acknowledgment to the camera sub-unit 11 (809). Thereafter, the PC 20 visually displays the maximum number of frames included in the CTS response on the monitor 22 (810).

By the above-described procedure, the PC 20 can confirm the maximum number of frames which can set in the taken image of the camera sub-unit 11, and can

additionally control the number of frames which can be set in the camera sub-unit 11 by the application of PC 20.

(2) Setting of Frame

5 In the embodiment, the application of the PC 20 can set a plurality of types of frames in the taken image of the camera sub-unit 11. A procedure for setting various frames will be described hereinafter with reference to Fig. 11.

10 (2-1) Setting of Rectangular Frame

 In the PC 20, the user starts the application to display a screen on the monitor 22 as shown in Fig. 2 (1101).

15 After the application is started, the user uses the operation unit 23 to operate the control button 2062, and selects a rectangular frame setting mode from a plurality of modes (1102).

20 In the rectangular frame setting mode, the user operates the operation unit 23, and sets a start point of the rectangular frame for the taken image on the preview screen 201. Subsequently, the user operates the operation unit 23 to set an end point of the rectangular frame. Thereby, a rectangular area with the start and end points being diagonal is determined
25 as in the frame 207 of Fig. 2 (1103).

 After the rectangular frame is set by the application, the PC 20 prepares CTS command to set the

rectangular frame (1104), and asynchronously transfers the CTS command to the camera sub-unit 11 (1105). In this case, the CTS command prepared in the PC 20 will be described with reference to Fig. 12.

5 In Fig. 12, in a ctype field 1201 is set "Control" which indicates that the command is a control command to control the camera sub-unit 11. Data specifying the camera sub-unit 11 of DVCR 10 are stored in Subunit_type field 1202 and Subunit ID field 1203.

10 Moreover, in Fig. 12, a code indicating a command "FRAME" concerning the frame control is set in an opcode field 1204. A code indicating an area setting command "Area Set" is set in an operand [0] field 1205. A frame number "Frame Number" arbitrarily set on the application is set in an operand [1] field 1206.

15 Furthermore, in Fig. 12, data indicating a frame type "Frame Type" is set in an operand [2] field. In an operand [3] field a value of X coordinate of the start point of the rectangular frame "X position of left top" is set, and in an operand [4] field a value of Y coordinate of the start point of the rectangular frame "Y position of left top" is set. In an operand [5] field a value of X coordinate of the end point of the rectangular frame "X position of right bottom" is set, and in an operand [6] field a value of Y coordinate of the end point of the rectangular frame "Y position of right bottom" is set.

After receiving the above-described CTS command, the camera sub-unit 11 returns an acknowledgment to the PC 20 (1106).

Moreover, the camera sub-unit 11 executes a processing corresponding to the received CTS command (1107), and additionally prepares CTS response corresponding to the CTS command (1108).

In this case, when the camera sub-unit 11 does not correspond to "Frame Number" and "Frame Type" designated by the CTS command, the DVCR 10 prepares CTS response by setting a response type "Rejected" or "Not Implemented" to the response field. Furthermore, when the camera sub-unit 11 corresponds to "Frame Number" and "Frame Type" designated by the CTS command, the DVCR 10 prepares CTS response by setting a response type "Accepted" to the response field.

Moreover, the camera sub-unit 11 stores the data specifying the sub-unit provided in the target in the Subunit_type field and Subunit ID field of the CTS response. In the opcode field and the operand [0] to operand [n] fields, the same values as those set in the CTS command are set, respectively.

After preparing the CTS response, the camera sub-unit 11 sets the CTS response in Asynchronous packet shown in Fig. 26, and transfers the packet to the PC 20 (1109). The PC 20 returns an acknowledgment of the CTS response to the camera sub-unit 11 (1110).

Subsequently, the PC 20 visually displays on the monitor 22 that the designated rectangular frame is set in the camera sub-unit 11 (1111).

By the above-described communication procedure,
5 the application of the PC 20 can set a rectangular frame area for the taken image of the camera sub-unit 11.

(2-2) Setting of Circular Frame

In the PC 20, the user starts the application to
10 display a screen on the monitor 22 as shown in Fig. 2 (1101).

After the application is started, the user uses the operation unit 23 to operate the control button 2063, and selects a circular frame setting mode from a
15 plurality of modes (1102).

In the circular frame setting mode, the user operates the operation unit 23, and sets a center point of the circular frame for the taken image on the preview screen 201. Subsequently, the user operates
20 the operation unit 23 to set range points of the circular frame. Thereby, a circular area in which a straight line connecting the center point and range points forms a radius is determined as in the frame 208 of Fig. 2 (1103).

25 After the circular frame is set by the application, the PC 20 prepares CTS command to set the circular frame (1104), and asynchronously transfers the

CTS command to the camera sub-unit 11 (1105). In this case, the CTS command prepared in the PC 20 will be described with reference to Fig. 13.

In Fig. 13, the data similar to those in Fig. 12 are set in a ctype field 1301, Subunit_type field 1302, Subunit ID field 1303, opcode field 1304, operand [0] field 1305, and operand [1] field 1306.

Moreover, in Fig. 13, data indicating a frame type "Frame Type" is set in an operand [2] field. In an operand [3] field a value of X coordinate of the center point of the circular frame "X position of center" is set, and in an operand [4] field a value of Y coordinate of the center point of the circular frame "Y position of center" is set. In an operand [5] field, a radius of the circular frame "radius" is set.

After receiving the above-described CTS command, the camera sub-unit 11 returns an acknowledgment to the PC 20 (1106).

Moreover, the camera sub-unit 11 executes a processing corresponding to the received CTS command (1107), and additionally prepares CTS response corresponding to the CTS command (1108). Additionally, for the CTS response, data are set in the same procedure as the CTS response of the rectangular frame.

After preparing the CTS response, the camera sub-unit 11 sets the CTS response in Asynchronous packet shown in Fig. 26, and transfers the packet to the PC 20

(1109). The PC 20 returns an acknowledgment of the CTS response to the camera sub-unit 11 (1110).

Subsequently, the PC 20 visually displays on the monitor 22 that the designated circular frame is set in the camera sub-unit 11 (1111).

By the above-described communication procedure, the application of the PC 20 can set a circular frame area for the taken image of the camera sub-unit 11.

(2-3) Setting of Polygonal Frame

In the PC 20, the user starts the application to display a screen on the monitor 22 as shown in Fig. 2 (1101).

After the application is started, the user uses the operation unit 23 to operate the control button 2064, and selects a polygonal frame setting mode from a plurality of modes (1102).

In the polygonal frame setting mode, the user operates the operation unit 23, and sets a start point of the polygonal frame for the taken image on the preview screen 201. Subsequently, the user operates the operation unit 23 to set a second point of the polygonal frame. Furthermore, the user operates the operation unit 23 to set third and subsequent points of the polygonal frame. Thereby, a polygonal area in which the start and second and subsequent points are sequentially connected by a straight line is determined as in the frame 209 of Fig. 2 (1103).

After the polygonal frame is set by the application, the PC 20 prepares CTS command to set the polygonal frame (1104), and asynchronously transfers the CTS command to the camera sub-unit 11 (1105). In this case, the CTS command prepared in the PC 20 will be described with reference to Fig. 14.

In Fig. 14, the data similar to those in Fig. 12 are set in a ctype field 1401, Subunit_type field 1402, Subunit ID field 1403, opcode field 1404, operand [0] field 1405, and operand [1] field 1406.

Moreover, in Fig. 14, data indicating a frame type "Frame Type" is set in an operand [2] field. In an operand [3] field the number of polygonal frame sides "Number of sides (n)" is set, and in operand [4] and subsequent fields a value of X coordinate of each apex "X position nth apex" and a value of Y coordinate "Y position nth apex" are set.

After receiving the above-described CTS command, the camera sub-unit 11 returns an acknowledgment to the PC 20 (1106).

Moreover, the camera sub-unit 11 executes a processing corresponding to the received CTS command (1107), and additionally prepares CTS response corresponding to the CTS command (1108). Additionally, in the CTS response, data are set in the same procedure as the CTS response of the rectangular frame.

After preparing the CTS response, the camera sub-

unit 11 sets the CTS response in Asynchronous packet shown in Fig. 26, and transfers the packet to the PC 20 (1109). The PC 20 returns an acknowledgment of the CTS response to the camera sub-unit 11 (1110).

5 Subsequently, the PC 20 visually displays on the monitor 22 that the designated polygonal frame is set in the camera sub-unit 11 (1111).

By the above-described communication procedure, the application of the PC 20 can set a polygonal frame area for the taken image of the camera sub-unit 11.

10 (2-4) Setting of Pixel Frame

In the PC 20, the user starts the application to display a screen on the monitor 22 as shown in Fig. 2 (1101).

15 After the application is started, the user uses the operation unit 23 to operate the control button 2065, and selects a pixel frame setting mode from a plurality of modes (1102).

In the pixel frame setting mode, the user operates
20 the operation unit 23, and sets a pixel frame of one pixel for the taken image on the preview screen 201. The pixel frame is set, for example, like the frame 210 of Fig. 2 (1103).

25 After the pixel frame is set by the application, the PC 20 prepares CTS command to set the pixel frame (1104), and asynchronously transfers the CTS command to the camera sub-unit 11 (1105). In this case, the CTS

command prepared in the PC 20 will be described with reference to Fig. 15.

In Fig. 15, the data similar to those in Fig. 12 are set in a ctype field 1501, Subunit_type field 1502, Subunit ID field 1503, opcode field 1504, operand [0] field 1505, and operand [1] field 1506.

Moreover, in Fig. 15, data indicating a frame type "Frame Type" is set in an operand [2] field. In an operand [3] field a value of X coordinate of the pixel frame "X position" is set, and in an operand [4] field a value of Y coordinate of the pixel frame "Y position" is set.

After receiving the above-described CTS command, the camera sub-unit 11 returns an acknowledgment to the PC 20 (1106).

Moreover, the camera sub-unit 11 executes a processing corresponding to the received CTS command (1107), and additionally prepares CTS response corresponding to the CTS command (1108). Additionally, in the CTS response, data is set in the same procedure as the CTS response of the rectangular frame.

After preparing the CTS response, the camera sub-unit 11 uses the CTS response to prepare Asynchronous transfer packet shown in Fig. 5, and asynchronously transfers the packet to the PC 20 (1109). The PC 20 returns an acknowledgment of the CTS response to the camera sub-unit 11 (1110).

Subsequently, the PC 20 visually displays on the monitor 22 that the designated pixel frame is set in the camera sub-unit 11 (1111).

By the above-described communication procedure,
5 the application of the PC 20 can set a pixel frame area for the taken image of the camera sub-unit 11.

(3) Inquiry of Frame Area

In the embodiment, the application of the PC 20 can inquire of the camera sub-unit 11 about the frame area which is set in the taken image of the camera sub-unit 11. A procedure for inquiring the frame area will be described hereinafter with reference to Fig. 16.

In the PC 20, the user starts the application to display a screen on the monitor 22 as shown in Fig. 2
15 (1601).

After the application is started, the user uses the operation unit 23 to select a desired frame from preset frames (1602). After the frame is selected, the user uses the operation unit 23 to instruct an inquiry
20 of the frame area (1603).

After confirming the user's instruction input, the PC 20 prepares CTS command to inquire the frame area (1604), and asynchronously transfers the CTS command to the camera sub-unit 11 (1605). In this case, the CTS
25 command prepared in the PC 20 will be described with reference to Fig. 17.

In Fig. 17, in a ctype field 1701 is set "Status"

which indicates that the command is a status command to inquire a state of the camera sub-unit 11. Data specifying the camera sub-unit 11 of DVCR 10 are stored in Subunit_type field 1702 and Subunit ID field 1703.

5 Moreover, in Fig. 17, a code indicating a command "FRAME" concerning the frame control is set in an opcode field 1704. A code indicating an area setting command "Area Set" is set in an operand [0] field 1705. A frame number "Frame Number" of a frame whose area information is to be inquired is set in an operand [1] field 1706.

10 After receiving the above-described CTS command, the camera sub-unit 11 returns an acknowledgment to the PC 20 (1606).

15 Moreover, the camera sub-unit 11 executes a processing corresponding to the received CTS command (1607), and additionally prepares CTS response corresponding to the CTS command (1608).

20 In this case, when the camera sub-unit 11 does not support "Frame Number" designated by the CTS command, the PC 20 prepares CTS response by setting "Rejected" to the response field. Furthermore, when the camera sub-unit 11 corresponds to "Frame Number" and "Frame Type" designated by the CTS command, the PC 20 prepares
25 CTS response by setting "Stable" to the response field.

 Moreover, the camera sub-unit 11 stores the data specifying the sub-unit provided in the target in the

Subunit_type field and Subunit ID field of the CTS response. In the opcode field and the operand [0] and operand [1] fields, the same values as those set in the CTS command are set, respectively.

5 Furthermore, in operand [2] and subsequent fields of the CTS response, the area of the designated frame is set using data formats shown in Figs. 12 to 15. When the area of the designated frame is not set, for example, dummy data like FF (hexadecimal) is set in the
10 operand [2] field.

After preparing the CTS response, the camera sub-unit 11 sets the CTS response in Asynchronous packet shown in Fig. 26, and transfers the packet to the PC 20 (1609).

15 The PC 20 returns an acknowledgment of the CTS response to the camera sub-unit 11 (1610). Thereafter, the PC 20 uses parameter information included in the CTS response to visually display the area of the selected frame on the monitor 22 (1611).

20 By the above-described procedure, the PC 20 can confirm the frame area which is set in the taken image of the camera sub-unit 11, and can additionally manage the frame area by the application of the PC 20.

(4) Switching of Display/Not-Display of Object Frame

25 In the embodiment, the application of the PC 20 can select whether or not the frame set in the taken image of the camera sub-unit 11 is

superimposed/displayed on the image. A procedure for switching displaying/not-displaying of the object frame will be described hereinafter with reference to Fig. 18.

5 In the PC 20, the user starts the application to display a screen on the monitor 22 as shown in Fig. 2 (1801).

10 After the application is started, the user uses the operation unit 23 to select an object or frame (1802). After the frame is selected, the user uses the operation unit 23 to instruct the displaying/not-

15 displaying of the frame (1803).
 After confirming the user's instruction input, the PC 20 prepares CTS command to switch the displaying/not-displaying (1804), and asynchronously transfers the CTS command to the camera sub-unit 11 (1805). In this case, the CTS command prepared in the PC 20 is shown in Fig. 19.

20 In Fig. 19, in a ctype field 1901 is set "Control" which indicates that the command is a control command to control the camera sub-unit 11. Data specifying the camera sub-unit 11 of DVCR 10 are stored in Subunit_type field 1902 and Subunit ID field 1903.

25 Moreover, in Fig. 19, a code indicating a command "FRAME" concerning the frame control is set in an opcode field 1904. A code designating the displaying/not-displaying "Show/Hide" is set in an

operand [0] field 1905. An object or frame number
"Frame Number" is set in an operand [1] field 1906.

After receiving the above-described CTS command,
the camera sub-unit 11 returns an acknowledgment to the
5 PC 20 (1806).

Moreover, the camera sub-unit 11 executes a
processing corresponding to the received CTS command
(1807), and additionally prepares CTS response
corresponding to the CTS command (1808).

10 In this case, when the camera sub-unit 11 supports
"Frame Number" designated by the CTS command, but the
area is not set in the object frame, the PC 20 prepares
CTS response by setting "Rejected" to the response
field. Furthermore, when the camera sub-unit 11
15 supports "Frame Number" designated by the CTS command,
and the area is set in the object frame, the PC 20
prepares CTS response by setting "Accepted" to the
response field.

Moreover, the camera sub-unit 11 stores the data
20 specifying the sub-unit of the target in Subunit_type
field and Subunit ID field of the CTS response. In the
opcode field and the operand [0] and operand [1]
fields, the same values as those set in the CTS command
are set, respectively.

25 After preparing the CTS response, the camera sub-
unit 11 sets the CTS response in Asynchronous packet
shown in Fig. 26, and transfers the packet to the PC 20

(1809).

The PC 20 returns an acknowledgment of the CTS response to the camera sub-unit 11 (1810). Thereafter, the PC 20 visually displays on the monitor 22 a taken
5 image to be isochronously transferred from the camera sub-unit and the object frame superimposed on the image (1811).

Here, when the CTS response with "Accepted" set therein is transferred, the camera sub-unit 11 switches
10 the displaying/not-displaying of the object frame.

For example, when the object frame is a rectangular, circular, or polygonal frame, and a code "Show" instructing the display of the frame is set in the operand [0] field of the CTS command, the camera
15 sub-unit 11 superimposes an outer rim of the object frame on the taken image, and isochronously transfers the taken image. Moreover, for the pixel frame, cross line display, circular rim display, rectangular rim display or another frame rim centering on the
20 designated pixel is superimposed and displayed on the taken image.

Thereby, the camera sub-unit 11 can supply to the PC 20 the image in which the outer rim of the object frame is superimposed beforehand on the taken image.
25 Moreover, when the DVCR 10 is equipped with a view finder, liquid crystal panel or another display unit, the image with the object frame superimposed on the

taken image is also displayed on the display unit.

Additionally, when a code "Hide" instructing the not-displaying of the frame is set in the operand [0] field of the CTS command, the camera sub-unit 11
5 isochronously transfers the taken image to the PC 20 without overlapping the frame rim of the object frame onto the taken image.

By the above-described procedure, the PC 20 can instruct the displaying/not-displaying of the frame
10 which is set in the taken image of the camera sub-unit 11, and can additionally manage the displaying/not-displaying of the frame by the application of the PC 20.

(5) Setting of Function of Object Frame

15 In the embodiment, for the camera sub-unit 11 the application of the PC 20 can set various functions of the frame set in the taken image of the camera sub-unit 11. A procedure for setting the function of the object frame will be described hereinafter with reference to
20 Fig. 20.

In the PC 20, the user starts the application to display a screen on the monitor 22 as shown in Fig. 2 (2001).

After the application is started, the user
25 operates the control button 2061 by the operation unit 23 to select a desired frame (2002). For example, after the control button 2061 is clicked using a mouse,

the frame 209 superimposed/displayed on the taken image on the preview screen 201 is double-clicked, so that the desired frame is selected.

After the frame is selected, the application of the PC 20 displays the menu window 211, thereby allowing the user to select various functions to be set to the object frame (2003). Here, examples of the functions which can be selected from the menu window 211 include auto-focusing, automatic exposure, white balance, digital zoom and the like.

After confirming the user's instruction input, the PC 20 prepares CTS command to set a predetermined function to the object frame (2004), and asynchronously transfers the CTS command to the camera sub-unit 11 (2005). In this case, the CTS command prepared in the PC 20 is shown in Fig. 21.

In Fig. 21, a control command "Control" to control the camera sub-unit 11 is set in a ctype field 2101. Data specifying the camera sub-unit 11 of DVCR 10 are stored in Subunit_type field 2102 and Subunit ID field 2103.

Moreover, in Fig. 21, a code indicating a command "FRAME" concerning the frame control is set in an opcode field 2104. A code indicating a function setting command "Function Set" is set in an operand [0] field 2105. A code "Frame Number" indicating an object frame number and a code "Function Type" indicating a

function to be set in the object frame are set in operand [1] and operand [2] fields 2106. Here, examples of "Function Type" include functions shown in Fig. 22.

5 After receiving the above-described CTS command, the camera sub-unit 11 returns an acknowledgment to the PC 20 (2006).

 Moreover, the camera sub-unit 11 executes a processing corresponding to the received CTS command (2007), and additionally prepares CTS response corresponding to the CTS command (2008).

10 In this case, when the camera sub-unit 11 does not support "Frame Number" and "Function Type" designated by the CTS command, the PC 20 prepares CTS response by setting "Rejected" to the response field. Furthermore, when the camera sub-unit 11 supports "Frame Number" and "Function type" designated by the CTS command, the PC 20 prepares CTS response by setting "Accepted" to the response field.

15 Moreover, the camera sub-unit 11 stores the data specifying the sub-unit of the target in Subunit_type field and Subunit ID field of the CTS response. In the opcode field and the operand [0] and operand [1] fields, the same values as those set in the CTS command are set, respectively.

20 After preparing the CTS response, the camera sub-unit 11 asynchronously transfers the CTS response to

the PC 20 (2009). After receiving the CTS response, the PC 20 returns an acknowledgment of the CTS response to the camera sub-unit 11 (2010).

Here, the camera sub-unit 11 sets the function of the object frame in response to the received CTS command. For example, when "Function Type" included in the CTS command is auto-focusing "Auto Focus", the camera sub-unit 11 auto-focuses the entire taken image based on the image of the object frame area, and isochronously transfers the result. Moreover, when "Function Type" included in the CTS command is digital zoom "Zoom", the camera sub-unit 11 zooms up the entire taken image based on the image of the object frame area, and isochronously transfers the result.

After returning the acknowledgment to the camera sub-unit 11, the PC 20 visually displays on the monitor 22 that the desired function is set in the object frame, and additionally displays the taken image prepared based on the function (2011).

For example, the application of the embodiment can change a color for displaying the outer rim of the object frame in accordance with the function selected/set by the user. In Fig. 2, when the function set in the frames 207 to 210 is the auto-focusing, the application displays the outer rim of the frame in red. When it is the white balance, the outer rim of the frame can be displayed in yellow. When such processing

is performed on each frame, the function set in each frame can be visually displayed, and user interface can be enhanced further.

When the user is to select another frame and to
5 set a desired function for the frame, by repeatedly performing the above-described procedure, various functions can be set for a plurality of frames.

By the above-described procedure, the PC 20 can
10 set various functions for the frame which is set in the taken image of the camera sub-unit 11, and can additionally manage the function of each frame by the application of the PC 20.

Additionally, in the embodiment, the case where
one function is set for the object frame has been
15 described, but the present invention is not limited thereto. The embodiment may be constructed in such a manner that CTS command for setting the function is set a plurality of times, or a plurality of function types are set in one CTS command, such CTS command is
20 transferred, and a plurality of functions are set for the object frame.

(6) Inquiry of Object Frame Function

In the embodiment, the application of the PC 20
can inquire of the camera sub-unit 11 about the
25 function of the frame which is set in the taken image of the camera sub-unit 11. A procedure for inquiring the function in the object frame will be described

hereinafter with reference to Fig. 23.

In the PC 20, the user starts the application to display a screen on the monitor 22 as shown in Fig. 2 (2301).

5 After the application is started, the user operates the control button 2061 or the like of the operation unit 23 to select an object or frame (2302). For example, after the control button 2061 is clicked using a mouse, the frame 209 superimposed/displayed on the taken image on the preview screen 201 is double-
10 clicked, so that the desired frame is selected.

After the object frame is selected, the user operates the operation unit 23 to instruct an inquiry of the frame function for the frame (2303).

15 After confirming the user's instruction input, the PC 20 prepares CTS command to inquire the object frame function (2304), and asynchronously transfers the CTS command to the camera sub-unit 11 (2305). In this case, the CTS command prepared in the PC 20 is shown in
20 Fig. 24.

In Fig. 24, in a ctype field 2401, a control command "Control" to control the camera sub-unit 11 is set. Data specifying the camera sub-unit 11 of DVCR 10 are stored in Subunit_type field 2402 and Subunit ID
25 field 2403.

Moreover, in Fig. 24, a code indicating a command "FRAME" concerning the frame control is set in an

opcode field 2404. A code indicating a function setting command "Function Set" is set in an operand [0] field 2405. A code indicating an object frame number "Frame Number" and dummy data "FF (hexadecimal)" are set in operand [1] and operand [2] fields 2406.

After receiving the above-described CTS command, the camera sub-unit 11 returns an acknowledgment to the PC 20 (2306).

Moreover, the camera sub-unit 11 executes a processing corresponding to the received CTS command (2307), and additionally prepares CTS response corresponding to the CTS command (2308).

In this case, when the camera sub-unit 11 does not support "Frame Number" designated by the CTS command, the PC 20 prepares CTS response by setting "Rejected" to the response field. Furthermore, when the camera sub-unit 11 supports "Frame Number" designated by the CTS command, the PC 20 prepares CTS response by setting "Stable" to the response field.

Moreover, the DVCR 10 stores the data specifying the sub-unit provided in the target in Subunit_type field and Subunit ID field of the CTS response. In the opcode field and the operand [0] and operand [1] fields, the same values as those set in the CTS command are set, respectively.

Furthermore, the DVCR 10 sets a code indicating the function set in the object frame into an operand

[2] field of the CTS response. Examples of the code include data shown in Fig. 22. When the function is not set in the object frame, dummy data FF (hexadecimal) is set.

5 After preparing the CTS response, the camera sub-unit 11 uses the CTS response to prepare Asynchronous transfer packet shown in Fig. 5, and asynchronously transfers the packet to the PC 20 (2309).

10 The PC 20 returns an acknowledgment of the CTS response to the camera sub-unit 11 (2310). Thereafter, the PC 20 visually displays the function of the object frame on the monitor 22 based on the CTS response (2311).

15 By the above-described procedure, the PC 20 can confirm the frame function set in the taken image of the camera sub-unit 11, and can additionally manage the function which can be set in each frame by the application of the PC 20.

20 Additionally, in the first embodiment, the present invention can variously be embodied without departing from spirits, or main characteristics thereof.

25 For example, in the embodiment, the storage medium 24 has been described as the hard disc, but is not limited thereto. The storage medium may be a floppy disc, optical disc, optical magnetic disc, CD-ROM, CD-R, magnetic tape, non-volatile memory card, ROM or the like as long as it can supply the program code for

realizing the embodiment to the control unit 21.

Moreover, the program code stored in the storage medium 24 of the embodiment may be recorded beforehand, or supplied from the outside via the digital interface 40 before recorded in the storage medium 24.

Therefore, the above-described embodiment is only an illustration in all respects, and should not be restrictedly construed.

Also, though the embodiment is explained according to an example, that is data communication system based upon the IEEE 1394 standard, the present invention can be applied to other data communication system. That is, it is possible to apply to data communication systems which can utilize a data communication method assuring real-time data transfer of the moving image data etc. as Isochronous transfer system and a data communication method transferring necessary information to a designated device without preventing the real-time data communication as Asynchronous transfer system.

As described above, according to the first embodiment, the setting and inquiring of the frame of the taken image of the target, and the setting and inquiring of various functions of the frame can be remote-operated from the controller.

Particularly, by the remote operation, the controller can confirm the maximum number of frames which can be set in the taken image of the target.

Moreover, by the remote operation, the controller can set a plurality of frames having different areas, or shapes for the taken image of the target.

Furthermore, by the remote operation, the controller can confirm the frame area which is preset in the taken image of the target.

Additionally, by the remote operation, the controller can instruct the displaying/not-displaying of the frame set in the taken image of the target.

Moreover, by the remote operation, the controller can set various functions for the frame set in the taken image of the target.

Furthermore, by the remote operation, the controller can confirm the function of the frame set in the taken image of the target.

(Second Embodiment)

In a second embodiment, an operation environment will be described in which IEEE 1394 serial bus or another network is connected to a target having a display unit and a controller for remote-operating the display unit, and the controller is used to control a displayed image of the display unit.

Moreover, in the second embodiment, an operation environment will be described in which IEEE 1394 serial bus or another network is connected to a target having a camera unit and a controller for remote-operating the camera unit, and the controller is used to control a

taken image of the camera unit.

Furthermore, in the second embodiment, an operation environment will be described in which IEEE 1394 serial bus or another network is connected to a first target having a display unit, a second target having a camera unit and a controller for remote-operating the display unit and the camera unit, and a displayed image of the display unit and a taken image of the camera unit are controlled.

In Figs. 25A and 25B, numeral 2510 denotes a computer, 2512 denotes an operation processing unit (MPU), 2514 denotes a first 1394 interface, 2516 denotes a first operation unit comprising a keyboard, mouse and the like, 2518 denotes a first decode, 2520 denotes CRT display or another display unit, 2522 denotes a hard disc, 2524 denotes a first memory, 2526 denotes PCI bus or another computer internal bus, and 2528 denotes a first 1394 interface terminal.

Numeral 2530 denotes a digital television (hereinafter referred to as DTV), 2532 denotes a second 1394 interface, 2534 denotes a first data selector, 2536 denotes a second operation unit, 2538 denotes a TV controller, 2540 denotes a second decode, 2542 denotes a second memory, 2544 denotes an image processing circuit, 2546 denotes a third memory, and 2548 denotes a display unit including a cathode ray tube (hereinafter referred to as CRT) and the like.

Numeral 2550 denotes a second 1394 interface terminal, 2552 denotes a third 1394 interface terminal, 2554 denotes an image input terminal, 2556 denotes a camera incorporating type digital video recorder (hereinafter referred to as DVCR), 2558 denotes an image pickup unit including an image pickup optical system, 2560 denotes an A/D converter, 2562 denotes a video processing unit, 2564 denotes a compression/expansion circuit, 2566 denotes a fourth memory, 2568 denotes a fifth memory, 2570 denotes a second data selector, and 2572 denotes a third 1394 interface.

Numeral 2574 denotes a memory control circuit, 2576 denotes a system controller, 2578 denotes a third operation unit, 2580 denotes an electronic view finder, 2582 denotes a D/A converter, 2584 denotes a recorder or another recording section (hereinafter referred to as the recorder), 2586 denotes a fourth 1394 interface terminal, and 2588 denotes EEPROM or another writable read only memory (hereinafter referred to as EEPROM).

The computer 2510, DTV 2530, and DVCR 2556 are nodes, and the nodes are interconnected via the first to third 1394 interfaces 2514, 2532, 2572. The nodes can transmit/receive data, or can mutually perform remote operation or the like by a command described later.

In the embodiment, for example, the computer 2510

operates as a controller for controlling a flow of image signals on the 1394 serial bus, or as a controller for remote-operating the DTV 2530 and DVCR 2556.

5 An internal constitution of the computer 2510 will next be described. The PCI bus or another computer internal bus 2526 is interconnected to the control unit (including MPU) 2512, 1394 interface 2514, first operation unit 2516, decoder 2518, display unit (including CRT display) 2520, hard disc 2522, internal memory 2524 and another device.

10 The control unit 2512 executes software recorded in the hard disc 2522, and additionally moves various data to the internal memory 2524. Moreover, the control unit 2512 also performs adjusting operation of the devices interconnected via the PCI bus 2526.

15 The 1394 interface 2514 receives an image signal transferred on the 1394 serial bus, and additionally transmits an image signal recorded in the hard disc 2522 and an image signal stored in the internal memory 2524 via the 1394 interface terminal 2528. The image signals are transmitted using Isochronous communication. Moreover, the 1394 interface 2514 asynchronously transfers CTS command for another apparatus connected on the 1394 serial bus via the first 1394 interface terminal 2528.

20 Moreover, the 1394 interface 2514 transfers a

signal transferred onto the 1394 serial bus to another 1394 node via the 1394 interface terminal 2528.

An operator allows the MPU 2512 to execute the software recorded in the hard disc 2522 through the operation unit 2516 comprising the keyboard, mouse and the like. The software and another information are presented to the operator by the display unit 2520 including the CRT display and the like.

The decoder 2518 decodes the image signal received from the 1394 serial bus through the software. The decoded image signal is also presented to the operator by the display unit 2520.

The inner constitution of the DTV 2530 will next be described.

In the embodiment, the DTV 2530 operates as an image output device. The second 1394 interface 2532 receives the image signal transferred onto the 1394 serial bus and command data for controlling the DTV 2530 via the 1394 serial bus, 1394 interface terminal 2550, and 1394 interface terminal 2552.

The image signal is received, for example, using Isochronous transfer. Moreover, the 1394 interface 2532 asynchronously transfers the CTS response to the CTS command. Furthermore, the 1394 interface 2532 transfers to another node the signal transferred onto the 1394 serial bus.

The received image data is transmitted to the

decoder 2540 through the data selector 2534. The decoder 2540 temporarily stores the image data in the memory 2542 to decode the data, and transmits an output to the image processing circuit 2544. The image processing circuit 2544 applies various processings to the decoded image data, then transmits an output to the display unit (including CRT) 2548 for display. Additionally, means constituting the display unit 2548 is not limited to the CRT, and needless to say, a liquid crystal display device, plasma device, or another display device can be used.

On the other hand, the received CTS command is transmitted to the TV controller 2538 through the data selector 2534. In response to the CTS command, the TV controller 2538 allows the data selector 2570 to switch input signals, allows the image processing circuit 2544 to control image qualities of output images, and performs other controls about various images. Moreover, the TV controller 2538 stores image quality control information of the output images in the memory 2546.

Moreover, for example, digital and analog image signals are transmitted from an image input apparatus (not shown) via the image input terminal 2554. The inputted digital signal is transmitted to the decoder 2540 through the data selector 2534.

The decoder 2540 temporarily stores the image data

in the memory 2542 to decode the data, and transmits an output to the image processing circuit 2544. The image processing circuit 2544 applies various processings to the decoded image data, then transmits an output to the display unit 2548 for display.

Switching of image input to any one of the 1394 interfaces 2550, 2552 and the image input terminal 2554 is performed by the data selector 2534. When the input terminal is set by the operation unit 2536, or the received CTS command, the TV controller 2538 instructs the data selector 2534 to set inputs. Following the instruction of the input setting, the data selector 2534 outputs an appropriate input signal.

An internal constitution of the DVCR 2556 will next be described.

In the embodiment, the DVCR 2556 operates as an input device of image signals. A luminance signal (Y) and color-difference signal (C) of the image transmitted from the image pickup unit 2558 are converted to digital data by the A/D converter 2560. The digital data is multiplexed by the video processing unit 2562. Subsequently, the data amount of the image information is compressed by the compression/expansion circuit 2564.

Generally, YC is independently provided with the compression processing circuit, but here for the simplicity of the description, an example of a

compression processing in YC time division is described. Subsequently, a shuffling processing is applied for the purpose of strengthening the image data against a transmission line error. An object of the processing is to convert a continuous code error or burst error to a random error as a discrete error which can easily be corrected or interpolated.

In addition, to make much of an object of uniforming a deviation of generation of information amount by coarseness in the image screen, when the processing is performed before the compression processing, run length or another variable length code is conveniently used. In response to this, data identification (ID) information for restoring the data shuffling is added.

The ID added by the ID adding operation, together with simultaneously recorded mode information and the like of the above-described system, is used as auxiliary information for a reverse compression processing (information amount expansion processing) during reproduction. In order to reduce an error during the reproduction of the data, error correction (ECC) information is added. The processing till the addition of such redundancy signal is applied for each independent record area corresponding to each image, voice or another information.

As described above, the image signal with ID and

ECC information added thereto is recorded in a magnetic tape or another recording medium by the recorder 2584, and additionally stored temporarily in the fourth memory 2566 described later.

5 On the other hand, the image data multiplexed by the video processing unit 2562 is digital-analog converted by the D/A converter 2582, and observed with the electronic view finder 2580 by the operator. Moreover, the operator transmits various operation
10 information to the system controller 2576 via the operation unit 2578. The system controller 2576 controls the entire DVCR 2556 by the operation information.

 Moreover, the image data multiplexed by the video
15 processing unit 2562 is transmitted to the memory 2568, and temporarily stored. Operations of the memories 2566 and 2568 are controlled by the system controller 2576 via the memory control circuit 2574.

 The data selector 2570 selects the data from the
20 memories 2566 and 2568 to transfer the data to the 1394 interface 2572, or selects the data from the 1394 interface 2532 to transfer the data to the memory 2566 or the memory 2568. By the above-described operation, from the 1394 interface 2572 in the DVCR 2556, the
25 compressed image data and non-compressed image data can be selected by the operator for Isochronous transfer.

 The 1394 interface 2572 receives CTS command for

controlling the DVCR 2556 via the 1394 serial bus and the 1394 interface terminal 2586. The received CTS command is transmitted to the system controller 2576 through the data selector 2570.

5 The system controller 2576 prepares CTS response for the CTS command, and transmits the CTS response to the 1394 serial bus through the data selector 2534 and the third 1394 interface 2572.

10 Moreover, in response to the command data, the system controller 2576 also performs a control on the recorder 2584 and the video processing unit 2562. The video processing unit 2562 adjusts the image quality of the video signal to be recorded by the control from the system controller 2576.

15 The image quality adjustment information is written in the EEPROM 2588, and can be stored even if main power of the DVCR 2556 is cut off. The writing of the image quality adjustment information into the EEPROM 2588 is performed, for example, when 1394
20 connector of an arbitrary apparatus in the bus is pulled off, or when a bus reset accompanied by the power cutting-off of the arbitrary apparatus in the bus is detected.

25 Figs. 27A and 27B show frame structures of CTS command and CTS response for use in the second embodiment.

 Fig. 27A shows the command frame structure, and

Fig. 27B shows the response frame structure.

In Fig. 27A, numeral 2750 denotes a command type (hereinafter referred to as ctype) field, 2752 denotes a sub-unit type (hereinafter referred to as subunit_type) field, 2754 denotes a sub-unit ID (hereinafter referred to as subunit_ID) field, and 2756 denotes an operation code (hereinafter referred to as opcode).

In Fig. 27A, after the opcode 2756, till the nth byte, each byte of operand [0], operand [1], ..., and operand [n] continues.

The ctype 2750 (4 bits) shows the command type. One example of a relationship of the value of the ctype 2750 and the command type is shown in the following Table 1.

[Table 1]

code (binary) MSB LSB		Command Type
0000		CONTROL
0001		STATUS
0010		SPECIFIC INQUIRY
0011		NOTIFY
0100		GENERAL INQUIRY
0101		(reserved)
0110		(reserved)
0111		(reserved)

In Table 1, when the value of the ctype 2750 is CONTROL, the controller controls the target. The control content is designated by the operand and opcode described later. Moreover, when the value of the ctype

2750 is STATUS, the controller inquires the current state of the target. The state is designated by the operand and opcode described later.

Moreover, when the value of the ctype 2750 is
5 NOTIFY, the controller notifies by the target that the state of the target is changed. The state is designated by the operand and opcode described later in the same manner as STATUS command.

Furthermore, when the value of the ctype 2750 is
10 SPECIFIC INQUIRY, or GENERAL INQUIRY, it is confirmed whether or not the CONTROL command having the same opcode is mounted on the target.

In the SPECIFIC INQUIRY command, the opcode and all operands have to be designated, but in the GENERAL
15 INQUIRY command, only the opcode is designated. This respect is a difference between the two INQUIRY commands.

With the subunit_type 2752 (5 bits) and the subunit_ID 2754 (3 bits), the sub-unit to which the CTS
20 command is to be sent is identified.

The subunit is a virtual entry which is identified as only one in one node (hereinafter referred to as the unit) and which provides a consistent function set.

One unit can have a plurality of subunits.
25 Therefore, the subunit_type 2752 and the subunit_ID 2754 indicate an address for identifying a certain subunit which is present in one unit.

The following Table 2 shows one example of a relationship of a value of subunit_type 2752 and a subunit type. The subunit_type 2752 and subunit_ID 2754 are generically referred to as a subunit address.

5 Additionally, when the value of the subunit_type 2752 is "1F₁₆" and the value of the subunit_ID 2754 is "3₁₆", the subunit address indicates the unit.

When the CTS command is transmitted to the display unit 2548 of the DTV 2530 in the embodiment, for example, a value "0000₂" is designated in the subunit_type 2752, and a value "000₂" is designated in the subunit_ID 2754. Moreover, when the command is transmitted to the camera unit 2558 of the DVCR 2556 in the embodiment, for example, a value "00111₂" is designated in the subunit_type 2752, and a value "000₂" is designated in the subunit_ID 2754. Furthermore, when the command is transmitted to a VCR subunit of the DVCR 2556 in the embodiment, a value "00100₂" is designated in the subunit_type 2752, and a value "000₂" is designated in the subunit_ID 2754.

The opcode 2756 defines a control content to be performed, and a state returned by the CTS response described later. The number and meaning of subsequent operands differ in accordance with the contents of the ctype, subunit_type and opcode.

[Table 2]

Code (binary) MSB LSB	Subunit Type
00000	Video Monitor
00001	(reserved)
00010	(reserved)
00011	disc recorder/player
00100	Video Cassette Recorder (VCR)
00101	Tuner
00110	(reserved)
00111	Video Camera
01000	(reserved)
:	
11011	
11100	Vendor unique
11101	(reserved)
11110	Extended subunit_type
11111	Unit

In Fig. 27B, the same reference numerals as those in Fig. 27A denote fields indicating the same functions. Moreover, in Fig. 27B, numeral 2758 denotes a response field (hereinafter referred to as response). The response 2758 indicates a CTS response type. Table 3 shows one example of a relationship of a value of response 2758 and the response type.

[Table 3]

code (binary) MSB LSB	Response
1000	NOT IMPLEMENTED
1001	ACCEPTED
1010	REJECTED
1011	IN TRANSITION
1100	IMPLEMENTED/STABLE
1101	CHANGED
1110	(reserved)
1111	INTERIM

The target prepares the corresponding CTS response by the ctype 2750, subunit address 2752, 2754, opcode

2756, and operand of the CTS command transmitted from the controller, and returns it to the controller.

The CTS command for remote-operating the DTV 2530 of the embodiment will next be described. In the embodiment, for example, CTS commands shown in Table 4 are defined. These are commands for controlling an image displayed by the display unit 2548 of the DTV 2530.

The commands shown in Table 4 are transferred to the target or DTV 2530 from the controller or computer 2510 by a procedure shown in Fig. 30. The procedure for remote-operating a display screen of DTV 2530 will be described hereinafter with reference to Fig. 30.

The controller 2512 of the computer 2510 reads a program stored in HD 2522, and starts an application for remote-operating the display unit of DTV 2530 (3001).

After the application is started, the user operates the operation unit 2516 to select a function to be controlled. The user can select six types of functions: APERTURE; BRIGHTNESS; CHROMA; CONTRAST; PHASE; and INPUT SIGNAL MODE. The CTS commands shown in Table 4 correspond to these functions, and each command is prepared in accordance with a user's request for operation (3002).

CTS command types shown in Table 4 and functions corresponding to the commands will be described

hereinafter.

[Table 4]

Name	opcode value
APERTURE	40 ₁₆
BRIGHTNESS	41 ₁₆
CHROMA	42 ₁₆
CONTRAST	43 ₁₆
PHASE	44 ₁₆
INPUT SIGNAL MODE	79 ₁₆

In Table 4, APERTURE is a command by which a contour compensating function on the display screen of the DTV 2530 is controlled and the current state is inquired. When the control is performed on the contour compensating function, CONTROL is set in the ctype 2750 of the CTS command. Moreover, when the current state is inquired for the contour compensating function, STATUS is set in the ctype 2750 of the CTS command.

With the APERTURE command with CONTROL being set therein, for example, one operand is designated. The controller or computer 2510 transmits the CTS command with a value of eight bits being set in the operand as APERTURE CONTROL command (3003).

Upon receiving the APERTURE CONTROL command, the DTV 2530 sets the contour compensation in accordance with the operand (3004). Additionally, the opcode value of the APERTURE command is not limited to "40₁₆", and another value may be defined. Moreover, the number of operands to be designated is not limited to one, and needless to say, one or more operands may be

designated.

In Table 4, BRIGHTNESS is a command by which the brightness on the display screen of the DTV 2530 is controlled and the current state is inquired. When the brightness on the display screen is controlled, CONTROL is set in the ctype 2750. Moreover, when the current state is inquired for the brightness on the display screen, STATUS is set in the ctype 2750.

With the BRIGHTNESS command with CONTROL being set therein, for example, one operand is designated. The controller or computer 2510 transmits the CTS command with a value of eight bits being set in the operand as BRIGHTNESS CONTROL command (3003).

Upon receiving the BRIGHTNESS CONTROL command, the DTV 2530 adjusts the brightness on the display screen in accordance with the operand (3004). For example, when the operand has a large value, the display screen is set bright. When the operand has a small value, the display screen is set dark. Additionally, the opcode value of the BRIGHTNESS command is not limited to "41₁₆", and another value may be defined. Moreover, the number of operands to be designated is not limited to one, and needless to say, one or more operands may be designated.

In Table 4, CHROMA is a command by which color density on the display screen of the DTV 2530 is controlled and the current state is inquired. When the

color density is controlled, CONTROL is set in the ctype 2750. Moreover, when the current state is inquired for the color density, STATUS is set in the ctype 2750.

5 With the CHROMA command with CONTROL set therein, for example, one operand is designated. The controller or computer 2510 transmits the CTS command with a value of eight bits set in the operand as CHROMA CONTROL command (3003).

10 Upon receiving the CHROMA CONTROL command, the DTV 2530 adjusts the color density on the display screen in accordance with the operand (3004). For example, when the operand has a large value, deep color is displayed. When the operand has a small value, light color is
15 displayed. Additionally, the opcode value of the CHROMA command is not limited to "42₁₆", and another value may be defined. Moreover, the number of operands to be designated is not limited to one, and one or more operands may be designated.

20 In Table 4, PHASE is a command by which tint on the display screen of the DTV 2530 is controlled and the current state is inquired. When the tint is controlled, CONTROL is set in the ctype 2750. Moreover, when the current state is inquired for the
25 tint, STATUS is set in the ctype 2750.

 With the PHASE command with CONTROL being set therein, for example, one operand is designated. The

controller or computer 2510 transmits the CTS command with a value of eight bits being set in the operand as PHASE CONTROL command (3003).

Upon receiving the PHASE CONTROL command, the DTV 2530 adjusts the tint on the display screen in accordance with the operand (3004). For example, when the operand has a large value, green is displayed strong. When the operand has a small value, purple is set to be displayed strong. Additionally, the opcode value of the PHASE command is not limited to "44₁₆", and another value may be defined. Moreover, the number of operands to be designated is not limited to one, and one or more operands may be designated.

In the above-described constitution, the image quality adjustment of the image displayed by the DTV 2530 on the 1394 serial bus can easily be remote-operated by the computer 2510 or another control device.

In Table 4, INPUT SIGNAL MODE is a command by which a type of an image signal to be transmitted to the DTV 2530 is designated, or a type of an image signal being transmitted to the DTV 2530 is inquired.

Fig. 28 is a view showing a data format of the INPUT SIGNAL MODE command on and after the opcode. In Fig. 28, signal_mode to be set in the operand [0] indicates the type of the input image signal. Table 5 shows codes to be set in the signal_mode and an example

of each content.

[Table 5]

Value	Signal mode
00 ₁₆	SD 525-60
04 ₁₆	SDL 525-60
08 ₁₆	HD 1125-60
80 ₁₆	SD 625-50
84 ₁₆	SDL 625-50
88 ₁₆	HD 1250-50
10 ₁₆	MPEG 25Mbps-60
14 ₁₆	MPEG 12.5Mbps-60
18 ₁₆	MPEG 6.25Mbps-60
90 ₁₆	MPEG 25Mbps-50
94 ₁₆	MPEG 12.5Mbps-50
98 ₁₆	MPEG 6.25Mbps-50
01 ₁₆	D-VHS Digital
05 ₁₆	Analog VHS NTSC 525/60
25 ₁₆	Analog VHS M-PAL 525/60
A5 ₁₆	Analog VHS PAL 625/50
B5 ₁₆	Analog VHS N-PAL 625/50
C5 ₁₆	Analog VHS SECAM 625/50
D5 ₁₆	Analog VHS ME-SECAM 625/50
0D ₁₆	Analog S-VHS 525/60
ED ₁₆	Analog S-VHS 625/50
30 ₁₆	Baseband 525-60/422 Component Digital
32 ₁₆	Baseband 525-60 Composite Digital
34 ₁₆	Baseband 525-60/411 Digital
B0 ₁₆	Baseband 625-50/422 Component Digital
B2 ₁₆	Baseband 625-50 Composite Digital
B4 ₁₆	Baseband 625-50/420 Digital

In the above-described constitution, the DTV 2530 of the embodiment can be adapted to various types of image signals, can know beforehand the type of the image signal to be inputted, and can notify another apparatus of the type of the image signal being inputted.

After the processing corresponding to each CTS command is executed, the controller 2538 of the DTV 2530 prepares the CTS response corresponding to the CTS

command (3005). Subsequently, the 1394 interface 2532 of the DTV 2530 packetizes the CTS response into Asynchronous packet shown in Fig. 26, and write transaction of the packet into a response register of the computer 2510 is performed (3006). The controller
5 2512 of the computer 2510 distinguishes the content of the CTS response, and displays a result of the CTS command on the display 2520 (3007).

By the above-described procedure, the computer 2510 can remote-operate the image displayed by the display unit 2548 of the DTV 2530, and can additionally
10 manage the displayed image of the display unit 2548 by the application of the computer 2510.

A command for remote-operating the DVCR 2556 of the embodiment will next be described. In the
15 embodiment, for example, commands shown in Table 6 are defined. These are commands for controlling an image taken by the image pickup unit 2558 of the DVCR 2556.

Each command shown in Table 6 is transferred to the target or DVCR 2556 from the controller or computer
20 2510 by a procedure shown in Fig. 31. A procedure for remote-operating a display screen of the DVCR 2556 will be described hereinafter with reference to Fig. 31.

The controller 2512 of the computer 2510 reads a program stored in the HD 2522, and starts an
25 application for remote-operating the image pickup unit of the DVCR 2556 (3101).

After the application is started, the user operates the operation unit 2516 to select a function to be controlled. The user can select eight types of functions: AE MODE; AE LOCK; APERTURE CORRECTION; GAIN; GAMMA; KNEE; WHITE BALANCE; and OUTPUT SIGNAL MODE. CTS commands shown in Table 6 correspond to these functions, and each command is prepared in response to the user's request for operation (3102).

Types of the CTS commands shown in Table 6 and the functions corresponding to the commands will be described hereinafter.

[Table 6]

Name	opcode value
AE MODE	40 ₁₆
AE LOCK	41 ₁₆
APERTURE CORRECTION	50 ₁₆
GAIN	51 ₁₆
GAMMA	52 ₁₆
KNEE	53 ₁₆
WHITE BALANCE	5D ₁₆
OUTPUT SIGNAL MODE	78 ₁₆

In Table 6, AE MODE CONTROL command is used to control an automatic exposure system. Moreover, AE MODE STATUS command is used to inquire the automatic exposure system.

Furthermore, AE LOCK CONTROL command is used to fix exposure to a constant value, i.e., to control so-called AE LOCK. Additionally, AE LOCK STATUS command is used to inquire the current AE LOCK state.

The APERTURE CORRECTION CONTROL command is used to

control the contour compensating function of the camera. Moreover, APERTURE CORRECTION STATUS command is used to inquire the current contour compensating function state of the camera.

5 The GAIN CONTROL command is used to control a gain of a signal processing system in the DVCR 2556. A value of the gain can be controlled for luminance, color difference, or RGB or another signal type. Moreover, GAIN STATUS command is used to inquire the
10 current gain value. In the same manner as the GAIN CONTROL command, GAIN STATUS command can inquire the gain value for the luminance, color difference, or RGB or another signal type.

 The GAMMA CONTROL command is used to control a
15 gamma value. The gamma value can be controlled for the luminance, color difference, or RGB or another signal type. Moreover, GAMMA STATUS command is used to inquire the current gamma value. In the same manner as the GAMMA CONTROL command, GAMMA STATUS command can
20 inquire the gamma value for the luminance, color difference, or RGB or another signal type.

 The KNEE CONTROL command is used to set a knee slope and knee point.

 The KNEE STATUS command is used to inquire the
25 current knee slope and knee point.

 The WHITE BALANCE CONTROL command is used to set a white balance of the camera. In the setting of the

white balance, parameters of both the color temperature conversion information and the setting in the current light source can be set. The WHITE BALANCE STATUS command is used to inquire the current camera white balance.

The OUTPUT SIGNAL MODE CONTROL command designates a type of a signal outputted by the camera sub-unit in the DVCR 2556. The OUTPUT SIGNAL MODE STATUS command is used to inquire the type of the signal outputted by the camera sub-unit in the DVCR 2556.

The OUTPUT SIGNAL MODE has one operand, and designates a type of a signal outputted by the operand. For a code value of the operand, the same value as the code value of the signal_mode field in the INPUT SIGNAL MODE command of the DTV 2530 is used.

After the processing corresponding to each CTS command is executed, the controller 2576 of the DVCR 2556 prepares CTS response corresponding to the CTS command (3105). Subsequently, the 1394 interface 2572 of the DVCR 2556 packetizes the CTS response into Asynchronous packet shown in Fig. 26, and write transaction of the packet into a response register of the computer 2510 is performed (3106). The controller 2512 of the computer 2510 distinguishes the content of the CTS response, and displays a result of the CTS command on the display 2520 (3107).

By the above-described procedure, the computer

2510 can remote-operate the image taken by the image pickup unit 2558 of the DVCR 2556, and can additionally manage the taken image of the image pickup unit 2558 by the application of the computer 2510.

5 Fig. 29 shows one example of a graphical user interface (hereinafter referred to as GUI) of an image quality setting application operated on the computer 2510. The application performs an image quality adjustment of the DTV 2530 using the above-described
10 CTS command.

 In Fig. 29, numeral 2970 denotes a monitor screen, 2972 denotes an image preview screen, 2974 denotes a brightness adjustment sliding bar for adjusting brightness, 2976 denotes a contrast adjustment sliding
15 bar for adjusting contrast, 2978 denotes a color adjustment sliding bar for adjusting tint, 2980 denotes a color density adjustment sliding bar for adjusting color density, and 2982 denotes a resolution adjustment sliding bar for adjusting resolution.

20 When the brightness adjustment sliding bar 2974 is moved to the right, for example, the brightness of the display surface of the DTV 2530 is set to become bright. The application generates an operand of the BRIGHTNESS CONTROL command in accordance with a
25 position of the brightness adjustment sliding bar 2974, and transmits the operand to the DTV 2530.

 When the contrast adjustment sliding bar 2976 is

moved to the right, for example, the contrast of the display surface of the DTV 2530 is set to become large. The application generates an operand of the CONTRAST CONTROL command in accordance with a position of the contrast adjustment sliding bar 2976, and transmits the operand to the DTV 2530.

When the color adjustment sliding bar 2978 is moved to the right, for example, the DTV 2530 is set to display green strong. When the bar is moved to the left, purple is displayed strong. The application generates an operand of the PHASE CONTROL command in accordance with a position of the color adjustment sliding bar 2978, and transmits the operand to the DTV 2530.

When the color density adjustment sliding bar 2980 is moved to the right, for example, the color of the DTV 2530 is set to become deep. The application generates an operand of the CHROMA CONTROL command in accordance with a position of the color density adjustment sliding bar 2980, and transmits the operand to the DTV 2530.

When the resolution adjustment sliding bar 2982 is moved to the right, for example, the contour compensating function is set strong in the display surface of the DTV 2530, and the resolution of the display surface is set high. Moreover, when the resolution adjustment sliding bar 2982 is moved to the

left, the contour compensating function is set weak,
and the resolution of the display surface is lowered.

The application generates an operand of the
APERTURE CONTROL command in accordance with a position
5 of the resolution adjustment sliding bar 2982, and
transmits the operand to the DTV 2530.

While observing the DTV 2530, or the preview
screen 2972, the operator of the application adjusts
the above-described plurality of adjustment bars 2974
10 to 2982 to adjust the image quality of the DTV 2530.

After the operator performs the image quality
adjustment of the DTV 2530, the computer application
generates a command of the DVCR 2556 corresponding to
the image quality setting of the DTV 2530 to transmit
15 the command to the DVCR 2556.

For example, when the brightness is adjusted by
the application, the GAIN CONTROL command and GAMMA
CONTROL command to the video camera sub-unit in the
DVCR 2556 are generated corresponding to the generated
20 BRIGHTNESS command to the DTV 2530, and transmitted to
the DVCR 2556.

Moreover, in the case where the brightness is
adjusted as described above, after the automatic
exposure mode is set by the AE MODE CONTROL command,
25 exposure may be set in accordance with the set
brightness by the AE LOCK CONTROL command.

Furthermore, when the tint is adjusted by the

application, the application generates the WHITE
BALANCE CONTROL command for the video camera unit in
response to the generated PHASE CONTROL command for the
DTV 2530, and transmits the command to the DVCR 2556.

5 Additionally, when the color density is adjusted
by the application, the application generates the GAIN
CONTROL command of the color-difference signal for the
video camera unit in response to the generated CHROMA
CONTROL command for the DTV 2530, and transmits the
10 command to the DVCR 2556.

 Moreover, when the resolution is adjusted by the
application, the application generates the APERTURE
CORRECTION CONTROL command for the video camera unit in
response to the generated APERTURE CONTROL command for
15 the DTV 2530, and transmits the command to the DVCR
2556.

 In the DVCR 2556, by the received camera command,
the system controller 2576 in the DVCR 2556 allows the
video processing unit 2562 to perform a processing
20 corresponding to the command, and stores the image
quality setting information in the EEPROM 2588. By the
above-described operation, the DVCR 2556 adjusts a
photographing image quality, and additionally holds the
image quality setting information even if the power
25 supply to the DVCR 2556 is cut off.

 By the above-described operation, the
communication device in the embodiment can set the

image quality of the DTV 2530 or another image output device, and can additionally reflect the content of the image quality setting in the photographing image quality setting of the DVCR 2556 or another photographing device and store the content.

Moreover, since the photographing image quality of the DVCR 2556 or another photographing device can be set on the DTV 2530 or another image output device, different from the prior art, the menu incorporated in the photographing device does not have to be used, and operating properties and visibility can remarkably be enhanced.

Furthermore, While the photographing device of the embodiment is connected to the 1394 bus, the image quality can be set. Therefore, the effect of the image quality adjustment can effectively be recognized easily. Additionally, the image output device of the embodiment is not limited to the DTV 2530 and needless to say, various image display devices such as a liquid crystal monitor, plasma display, and another monitor device can be used.

Moreover, there is a demerit that a stand-by time is lengthened by a printing time, but needless to say, a printer, copying machine and the like can be used.

Furthermore, the photographing device of the embodiment can be applied not only to the camera incorporating type VCR and another video camera but

also to a still video camera, digital camera and any other photographing device. Moreover, the device is not limited to the camera device, and needless to say, the device can be applied to a film scanner, flat bed scanner or another scanner device, or to a draft scanner section of the copying machine or the like.

Moreover, the control node of the embodiment is not limited to the computer or another electronic calculator, and needless to say, another apparatus may be used. Furthermore, the control node of the embodiment does not have to be an independent apparatus, and needless to say, either the image output device or the photographing device may be constituted to operate as the control node.

Also, though the embodiment is explained according to an example, that is data communication system based upon the IEEE 1394 standard, the present invention can be applied to other data communication system. That is, it is possible to apply to data communication systems which can utilize a data communication method assuring real-time data transfer of the moving image data etc. as Isochronous transfer system and a data communication method transferring necessary information to a designated device without preventing the real-time data communication as Asynchronous transfer system.

(Other Embodiments of the Invention)

The present invention may be applied to a system

constituted of a plurality of apparatuses (e.g., host computer, interface apparatus, reader, printer and the like), or to a device constituted of one apparatus.

Moreover, in order to operate various devices to realize the above-described function of the embodiment, the program code of the software for realizing the function of the embodiment is supplied to a device connected to the various devices, or to the computer in the system, so that the various devices are operated in accordance with the program stored in the system or in the computer of the device (CPU or MPU). Such implementation is also included in the category of the present invention.

Furthermore, in this case, the program code itself of the software realizes the function of the embodiment, and the program code itself, and means for supplying the program code to the computer, e.g., the storage medium with the program code stored therein constitute the present invention. As the storage medium for storing the program code, for example, a floppy disc, hard disc, optical disc, optical magnetic disc, CD-ROM, magnetic tape, non-volatile memory card, ROM, or the like can be used.

Moreover, when the computer executes the supplied program code, the above-described function of the embodiment is realized. Additionally, the program code cooperates with OS (operating system) operated in the

computer or another application software to realize the function of the embodiment. Needless to say, such program codes are included in the embodiment of the present invention.

5 Furthermore, after the supplied program code is stored in a memory provided in a function expansion board of a computer or a function expansion unit connected to the computer, based on an instruction of the program code, CPU or the like provided in the
10 function expansion board or the function expansion unit performs a part or the whole of the actual processing, and by the processing the above-described function of the embodiment is realized. Needless to say, this case is also included in the present invention.

15 In the second embodiment, as described above, when various data are transmitted/received among a plurality of terminal devices connected via the data communication bus to perform a predetermined processing, the image quality adjustment data is
20 transmitted via the data communication bus, and operation is performed in accordance with the image quality adjustment data in the terminal device which has received the image quality adjustment data.
Therefore, the image quality setting of the image
25 display device can be remote-operated, and the operating properties and visibility can remarkably be enhanced. Moreover, according to other characteristics

of the present invention, the content of the image
quality setting can be reflected on the side of the set
terminal device. Furthermore, according to other
characteristics of the present invention, the content
5 of the image quality setting can be stored in the
storage means.

Moreover, according to the second embodiment,
since the image quality adjustment data transmitted via
the data communication bus is received to change the
10 photographing image quality, the content of the image
quality setting of the image display device can be
reflected in the photographing image quality setting of
the photographing device. Furthermore, according to
other characteristics of the present invention, the
15 content of the photographing image quality setting can
be stored in the storage medium. Thereby, without
using the menu or the like incorporated in the
photographing device, the photographing image quality
can be set by the remote operation, and the operating
20 properties and visibility of the photographing device
can remarkably be enhanced.

Moreover, according to the second embodiment,
while the photographing device is connected to the 1394
bus, the image quality setting can be performed, so
25 that the effect of the image quality adjustment can
easily be recognized.

WHAT IS CLAIMED IS:

1. A data communication system, comprising:

a target having an image pickup unit;

a controller for remote-operating said image

5 pickup unit;

a data line for connecting said target and said
controller, said data line supporting a first
communication mode and a second communication mode; and

10 a control command for setting a predetermined area
in an image outputted by said image pickup unit,

wherein said target transmits said image by using
said first communication mode, and said controller
transmits said control command by using second
communication mode.

15

2. A data communication system according to claim

1,

wherein said control command sets in said image
any one of an area of a rectangular shape, an area of a
20 circular shape, an area of a polygonal shape, and an
area of one pixel unit.

3. A data communication system according to claim
1, further comprising:

25 a second control command for controlling at least
one of focus, exposure, white balance, and digital zoom
of said image pickup unit based on the area set in said

image.

4. A data communication system according to claim 1, further comprising:

5 a status command for inquiring a state of the area set in said image.

5. A data communication system according to claim 1,

10 wherein said first communication mode and said second communication mode are executed in time division.

15 6. A data communication system according to claim 1,

 wherein in one communication cycle period, said first communication mode has a higher priority than said second communication mode.

20 7. A data communication system according to claim 1,

 wherein said first communication mode is executed each one communication cycle period.

25 8. A data communication system according to claim 1,

 wherein said first communication mode is an

Isochronous transfer mode, and said second communication mode is an Asynchronous transfer mode.

9. A data communication system according to claim

5 1,

wherein said target is a camera integrated type digital video recorder.

10. A data communication system according to

10 claim 1,

wherein said data line conforms to IEEE 1394-1995 standards.

11. A data communication control method,

15 comprising the steps of:

transmitting, by a target, an image outputted by an image pickup unit using a first communication mode supported by a data line; and

20 transmitting, by a controller, a control command for setting a predetermined area in said image to said target using a second communication mode supported by said data line, said controller remote-operating said image pickup unit.

25 12. An electronic apparatus, comprising:

an image pickup unit for outputting an image; and communication means for communicating with a

controller connected to a data line, said controller remote-operating said image pickup unit, said data line supporting a first communication mode and a second communication mode,

5 wherein said communication means transmits said image by using said first communication mode, and receives a control command from said controller by using second communication mode, and said image pickup unit sets a predetermined area in said image based on
10 said control command.

13. A data communication control method, comprising the steps of:

transmitting an image from an image pickup unit by
15 using a first communication mode supported by a data line; and

receiving a control command for setting a predetermined area in said image by using a second communication mode supported by said data line,
20 transmitting said control command by a controller to remote-operate said image pickup unit.

14. An electronic apparatus, comprising:

means for remote-operating an image pickup unit of
25 a target connected to a data line, said data line supporting a first communication mode and a second communication mode; and

communication means for transmitting a control command for setting a predetermined area in an image outputted by said image pickup unit, said image being transmitted using said first communication mode,

5 wherein said communication means transmits said control command by using said second communication mode.

15. A data communication system, comprising:
10 a target having a display unit;
 a controller for remote-operating said display unit;

 a data line for connecting said target and said controller, the data line supporting a first
15 communication mode and a second communication mode; and

 a control command for regulating an image displayed by said display unit,

 wherein said target receives said image by using said first communication mode, and said controller
20 transmits said control command by using said second communication mode.

16. A data communication control method,
comprising the steps of:

25 receiving, by a target, an image displayed by a display unit using a first communication mode supported by a data line; and

transmitting, by a controller, a control command for regulating said image to said target using a second communication mode supported by said data line, said controller remote-operating said display unit.

5

17. An electronic apparatus, comprising:
a display unit for displaying an image; and
communication means for communicating with a controller connected to a data line, said controller remote-operating said display unit, said data line supporting a first communication mode and a second communication mode,

10

15

wherein said communication means receives said image by using said first communication mode, and receives a control command from said controller by using said second communication mode, and wherein said display unit regulates said image based on said control command.

20

18. A data communication control method, comprising the steps of:

receiving an image displayed by a display unit using a first communication mode supported by a data line; and

25

receiving a control command for regulating said image using a second communication mode supported by said data line, transmitting said control command by a

controller to remote-operate said display unit.

19. An electronic apparatus, comprising:

means for remote-operating a display unit of a
5 target connected to a data line, said data line
supporting a first communication mode and a second
communication mode; and

communication means for transmitting a control
command for regulating an image displayed by said
10 display unit, said image being transmitted using said
first communication mode,

wherein said communication means transmits said
control command by using said second communication
mode.

20. A data communication system, comprising:

a target having an image pickup unit;

a controller for remote-operating said image
pickup unit;

20 a data line for connecting said target and said
controller, the data line supporting a first
communication mode and a second communication mode; and

a control command for regulating an image
outputted by said image pickup unit,

25 wherein said target transmits said image by using
said first communication mode, and said controller
transmits said control command by using said second

communication mode.

21. A data communication control method,
comprising the steps of:

5 transmitting, by a target, an image outputted by
an image pickup unit using a first communication mode
supported by a data line; and

10 transmitting, by a controller, a control command
for regulating said image using a second communication
mode supported by said data line, said controller
remote-operating said image pickup unit.

22. An electronic apparatus, comprising:
an image pickup unit for outputting an image; and
15 communication means for communicating with a
controller connected to a data line, said controller
remote-operating said image pickup unit, said data line
supporting a first communication mode and a second
communication mode,

20 wherein said communication means transmits said
image by using said first communication mode, and
receives a control command from said controller by
using said second communication mode, and said image
pickup unit regulates said image based on said control
25 command.

23. A data communication control method,

comprising the steps of:

transmitting an image outputted by an image pickup unit using a first communication mode supported by a data line; and

5 receiving a control command for regulating said image using a second communication mode supported by said data line, transmitting said control command by a controller to remote-operate said image pickup unit.

10 24. An electronic apparatus, comprising:

means for remote-operating an image pickup unit of a target connected to a data line, said data line supporting a first communication mode and a second communication mode; and

15 communication means for transmitting a control command for regulating an image outputted by said image pickup unit, said image being transmitted using said first communication mode,

20 wherein said communication means transmits said control command by using the second communication mode.

ABSTRACT OF THE DISCLOSURE

A controller and target are connected to a network which can transmit an animated image signal in real time. To remote-operate a function of the target from the controller, some commands, responses, and transaction procedure are determined. As a result, the controller sets one or more areas in a taken image of the target, and can adjust an image quality for the area. Moreover, the controller can adjust the image quality of a displayed image of the target. Furthermore, the controller can adjust the image quality of the taken image of the target.

FIG. 1

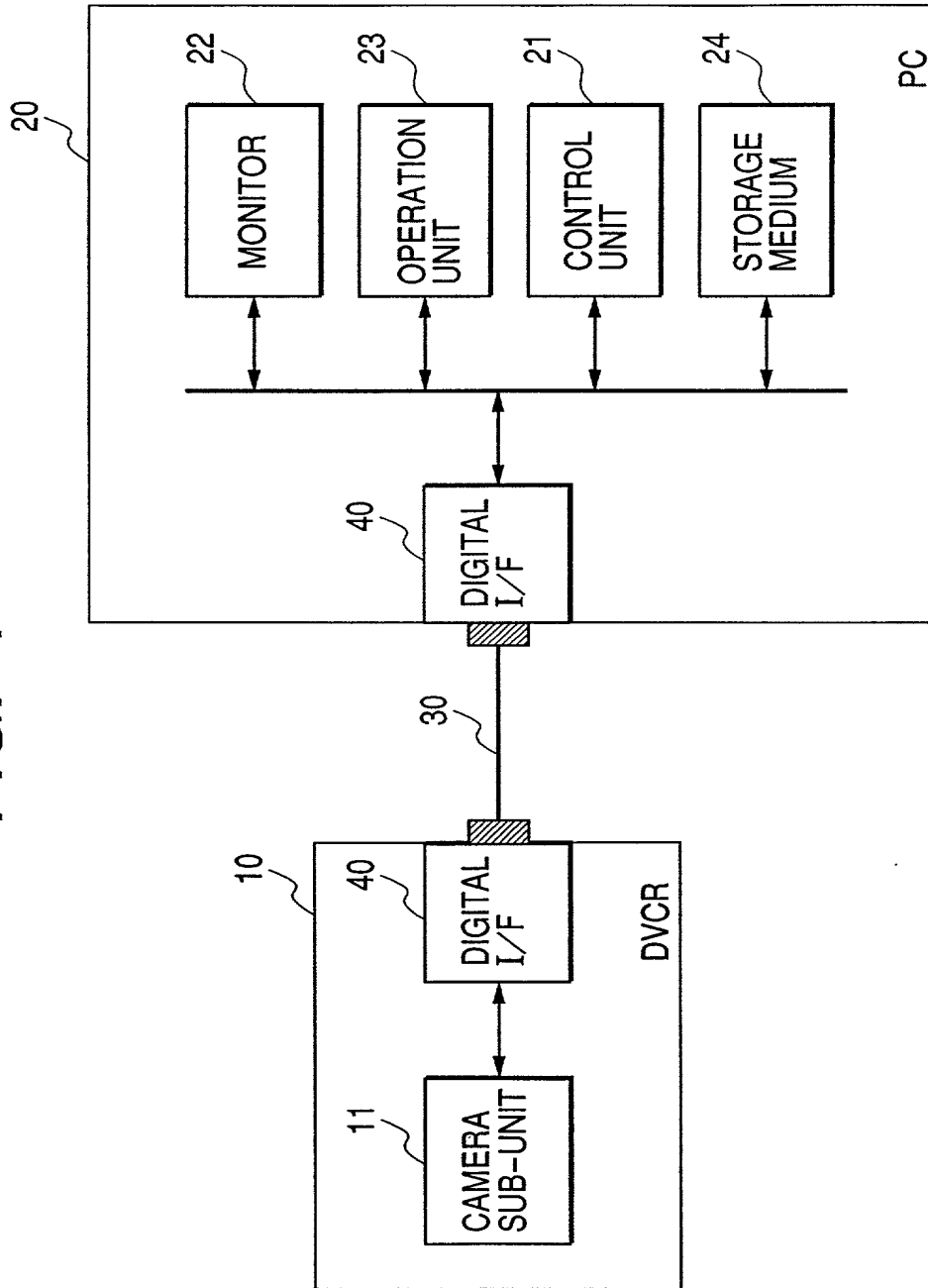
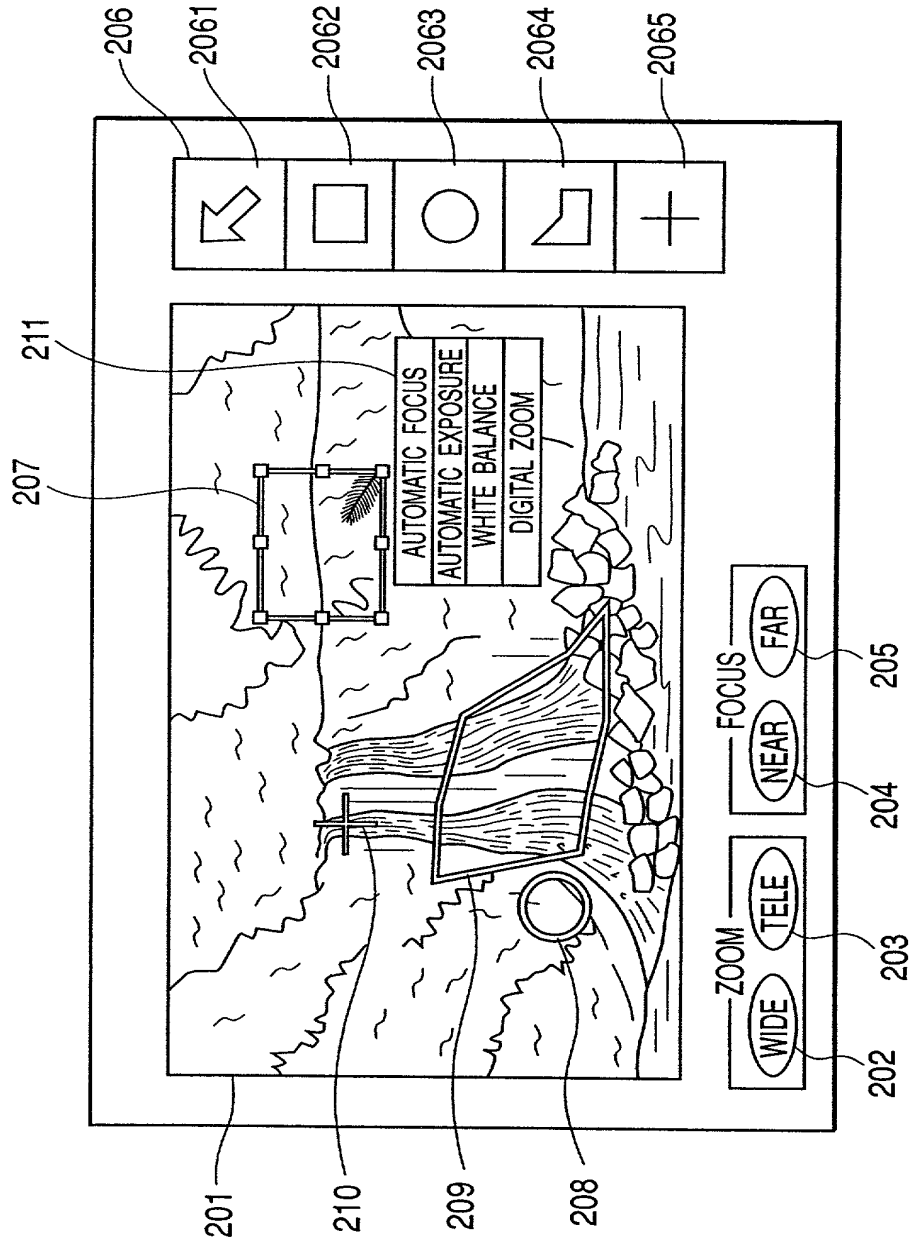


FIG. 2



CONTROL COMMAND

AE MODE	AUTOMATIC EXPOSURE MODE
CC FILTER	COLOR CORRECTION FILTER
DIGITAL ZOOM	DIGITAL ZOOM
FADER	FADER
FOCAL LENGTH	FOCAL LENGTH CONTROL
FOCUS	MOVING CONTROL OF FOCUS LENS
FOCUSSING MODE	FOCUSSING MODE
FOCUSSING POSITION	FOCUSSING LENS POSITION CONTROL
FRAME	FRAME WITHIN IMAGE
GAIN	GAIN
GAMMA	GAMMA
IMAGE STABILIZER	VIBRATION CONTROL
INFRARED	INFRARED LIGHT PROCESS SWITCHING
IRIS	APERTURE
KNEE	KNEE POINT, KNEE SLOPE
ND FILTER	NEUTRAL DENSITY FILTER
OUTPUT SIGNAL MODE	OUTPUT DATA SIGNAL FORMAT
PAN/TILT/ROLL	TRIPOD HEAD CONTROL
SCAN MODE	CCD READING METHOD
SHIFT	SHIFT AMOUNT AND DIRECTION OF MANIPULATION
SHUTTER	SHUTTER SPEED
TILT	TILT AMOUNT AND DIRECTION OF MANIPULATION
VIDEO LIGHT/STROBE	VIDEO LIGHT, STROBE
WHITE BALANCE	WHITE BALANCE
ZOOM	ZOOMING

FIG. 3B

STATUS COMMAND

AE MODE	AUTOMATIC EXPOSURE MODE
CC FILTER	COLOR CORRECTION FILTER
DIGITAL ZOOM	DIGITAL ZOOM
FADER	FADER
FOCAL LENGTH	FOCAL LENGTH CONTROL
FOCUS	MOVING CONTROL OF FOCUS LENS
FOCUSSING MODE	FOCUSSING MODE
FOCUSSING POSITION	FOCUSSING LENS POSITION CONTROL
FRAME	FRAME WITHIN IMAGE
GAIN	GAIN
GAMMA	GAMMA
IMAGE STABILIZER	VIBRATION CONTROL
INFRARED	INFRARED LIGHT PROCESS SWITCHING
IRIS	APERTURE
KNEE	KNEE POINT, KNEE SLOPE
ND FILTER	NEUTRAL DENSITY FILTER
OUTPUT SIGNAL MODE	OUTPUT DATA SIGNAL FORMAT
PAN/TILT/ROLL	TRIPOD HEAD CONTROL
SCAN MODE	CCD READING METHOD
SHIFT	SHIFT AMOUNT AND DIRECTION OF MANIPULATION
SHUTTER	SHUTTER SPEED
TILT	TILT AMOUNT AND DIRECTION OF MANIPULATION
VIDEO LIGHT/STROBE	VIDEO LIGHT, STROBE
WHITE BALANCE	WHITE BALANCE
ZOOM	ZOOMING
DISTORTION	DISTORTION ABERRATION INFORMATION
FADER INFO	PRESET FADER INFORMATION
PEDESTAL	PEDESTAL
SHADING	PERIPHERAL SHADING
WHITE BALANCE INFO	PRESET WHITE BALANCE INFORMATION

FIG. 3C

NOTIFY COMMAND

CC FILTER	COLOR CORRECTION FILTER
DIGITAL ZOOM	DIGITAL ZOOM
FADER	FADER
FOCAL LENGTH	FOCAL LENGTH CONTROL
FOCUS	MOVING CONTROL OF FOCUSING LENS
ND FILTER	NEUTRAL DENSITY FILTER
PAN/TILT/ROLL	TRIPOD HEAD CONTROL
SHIFT	SHIFT AMOUNT AND DIRECTION OF MANIPULATION
TILT	TILT AMOUNT AND DIRECTION OF MANIPULATION
VIDEO LIGHT/STROBE	VIDEO LIGHT, STROBE
ZOOM	ZOOMING

FIG. 4

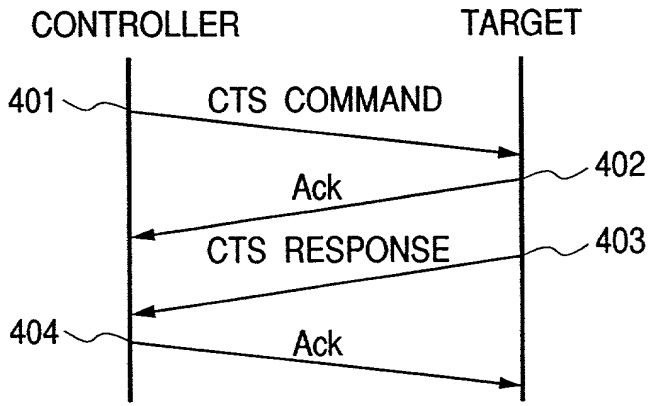
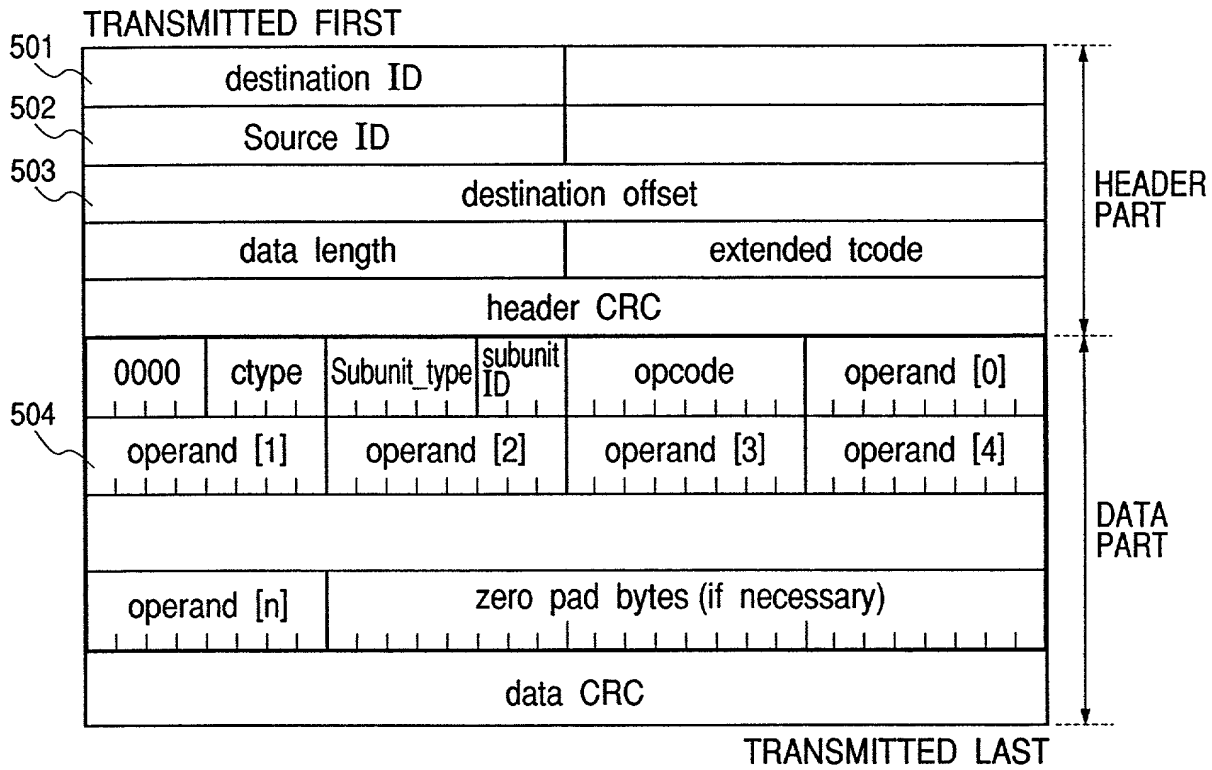


FIG. 5A**FIG. 5B**

VALUE	COMMAND TYPE	MEANING
0	CONTROL	CONTROL COMMAND
1	STATUS	DEVICE STATUS INQUIRY
2	INQUIRY	INQUIRY OF SUPPORT STATUS OF THE COMMAND
3	NOTIFY	DEVICE STATUS CHANGE NOTIFICATION

FIG. 6

opcode	Frame
operand [0]	Subfunction
operand [1]	Frame Number
operand [2]	Parameters
operand [3]	
⋮	
operand [n]	

FIG. 7A

TRANSMITTED FIRST

0000	response	Subunit_type	subunit ID	opcode	operand [0]
operand [1]		operand [2]		operand [3]	operand [4]
operand [n]		zero pad bytes (if necessary)			

TRANSMITTED LAST

FIG. 7B

VALUE	RESPONSE TYPE	MEANING
8	NOT IMPLEMENTED	THE COMMAND IS NOT SUPPORTED
9	ACCEPTED	COMMAND WAS ACCEPTED
A16	REJECTED	COMMAND WAS REJECTED
F16	INTERIM	RETURN RESPONSE LATER

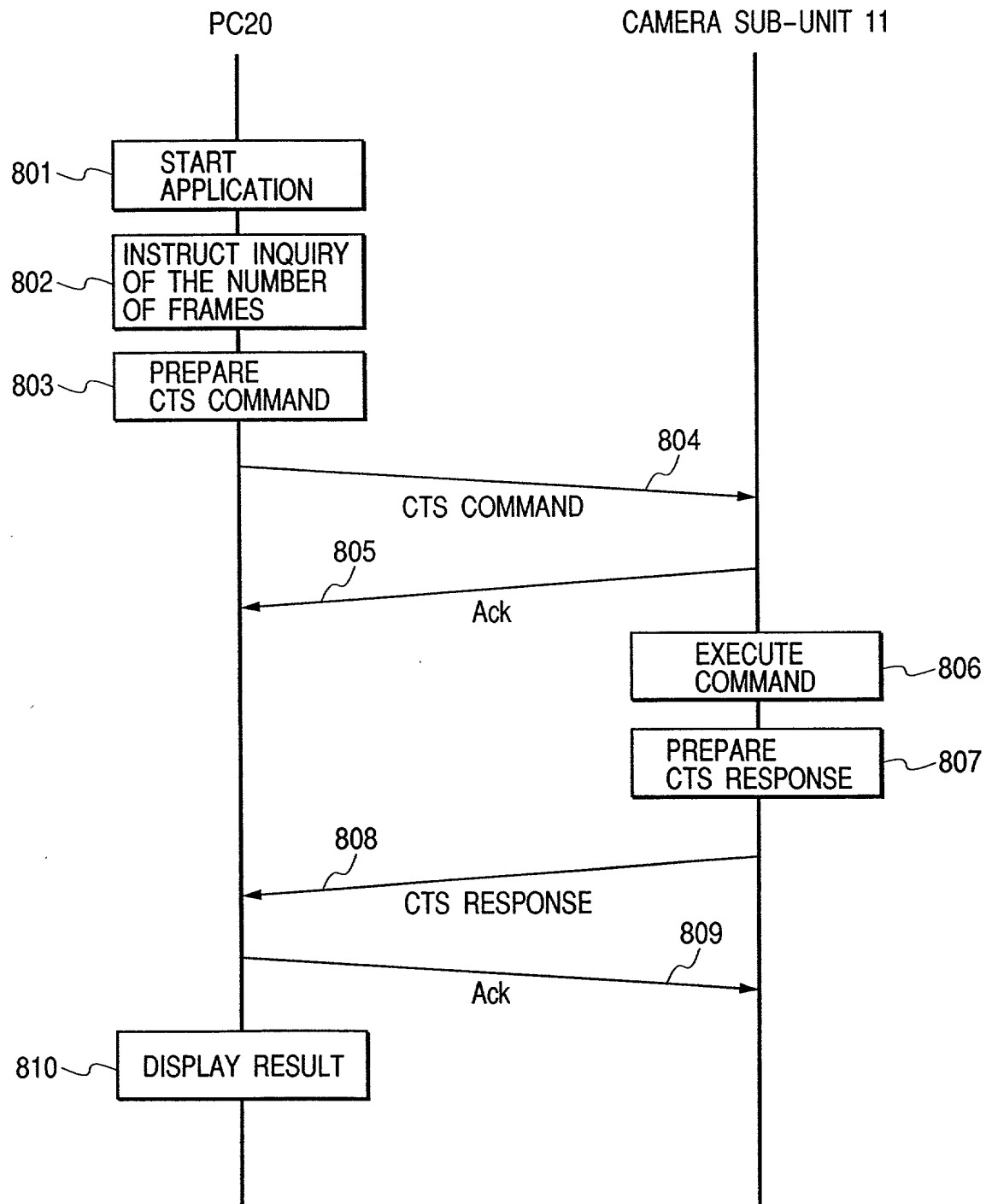
FIG. 8

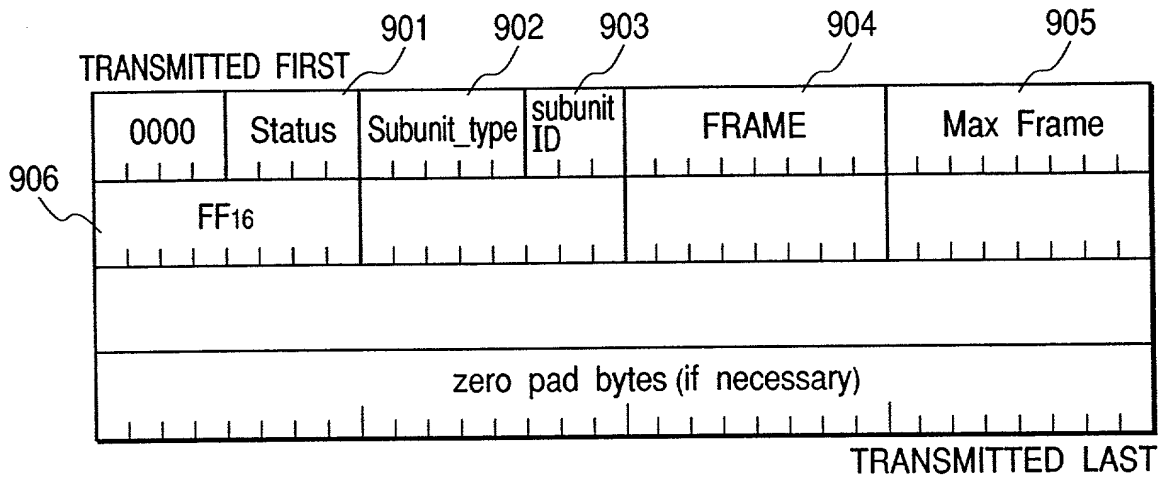
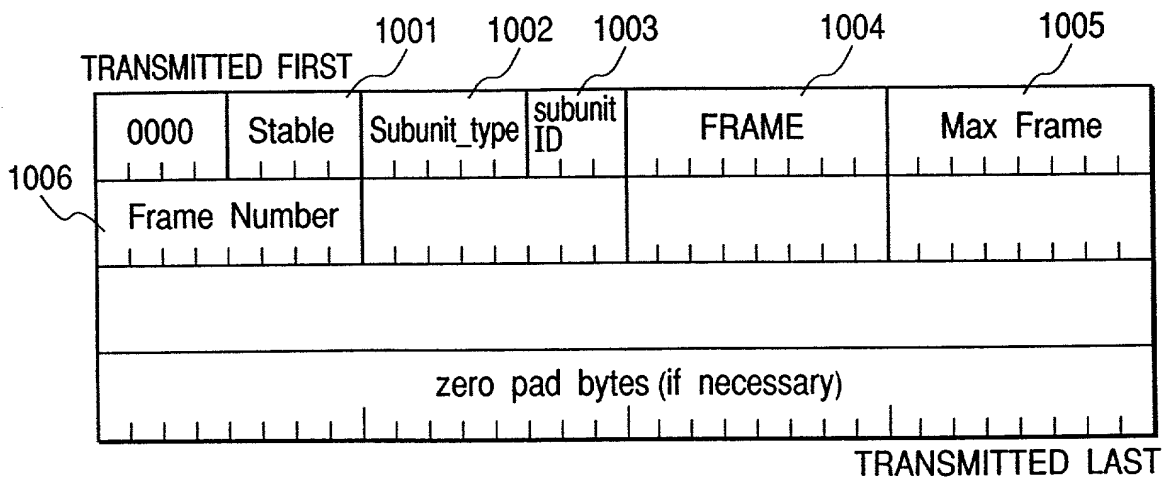
FIG. 9**FIG. 10**

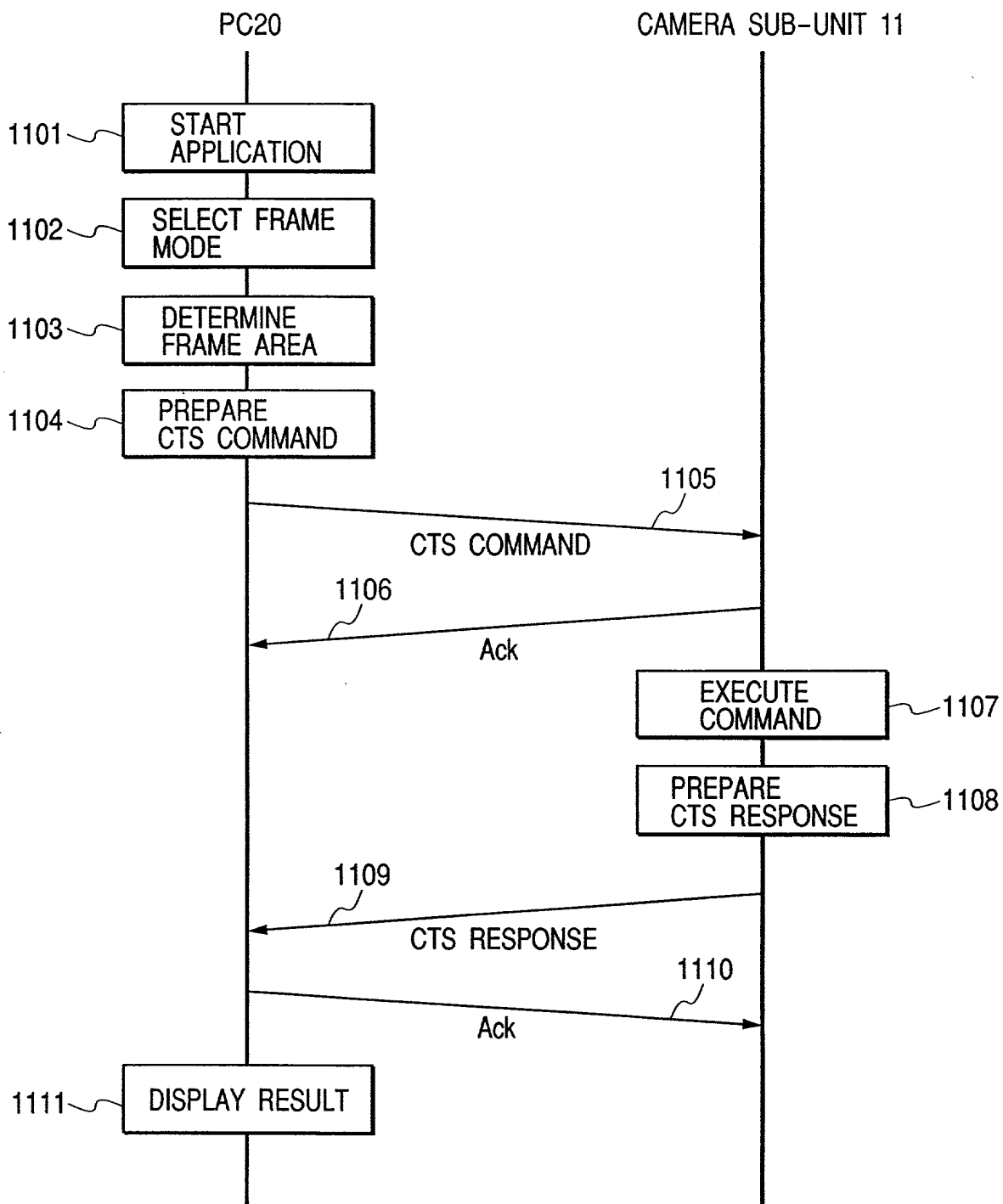
FIG. 11

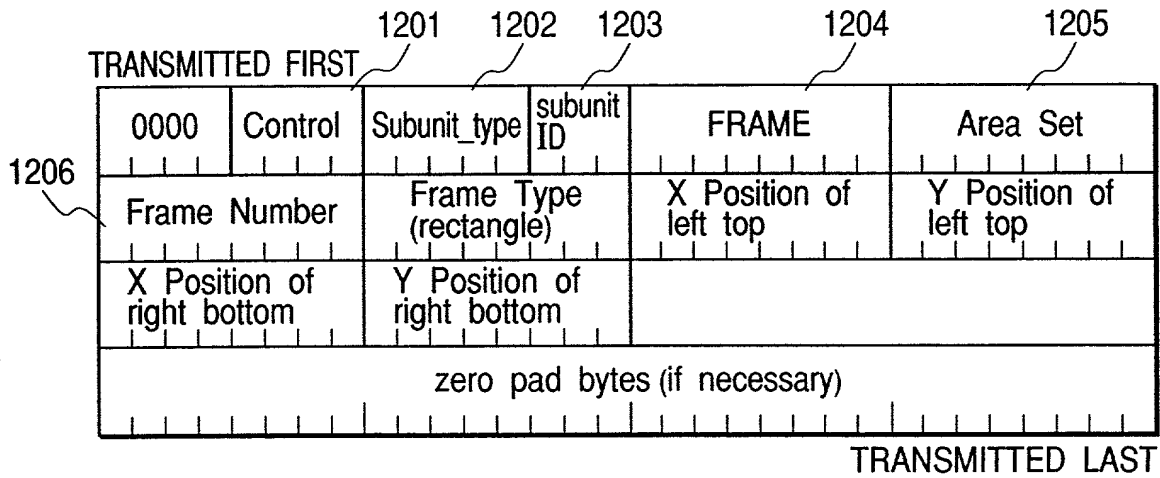
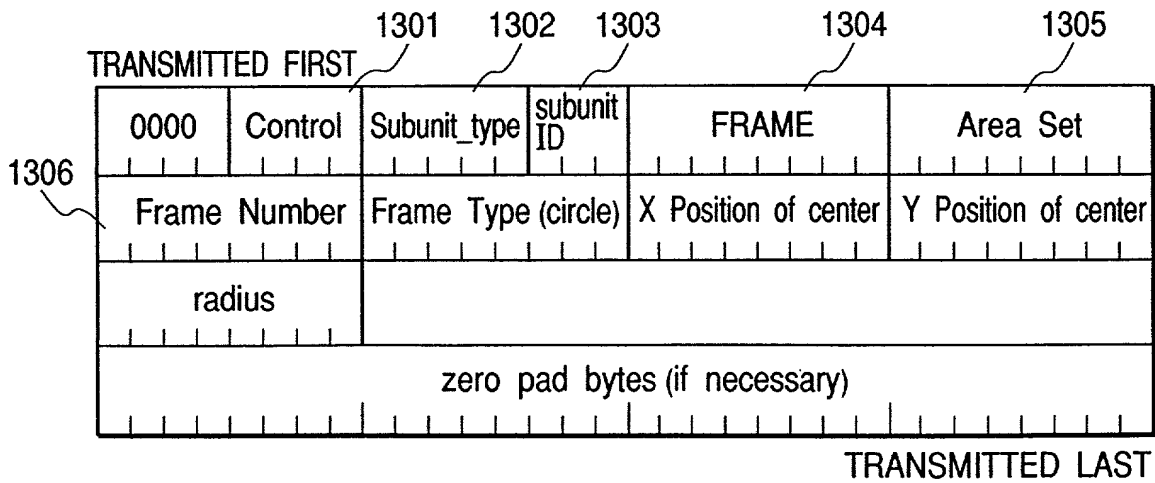
FIG. 12**FIG. 13**

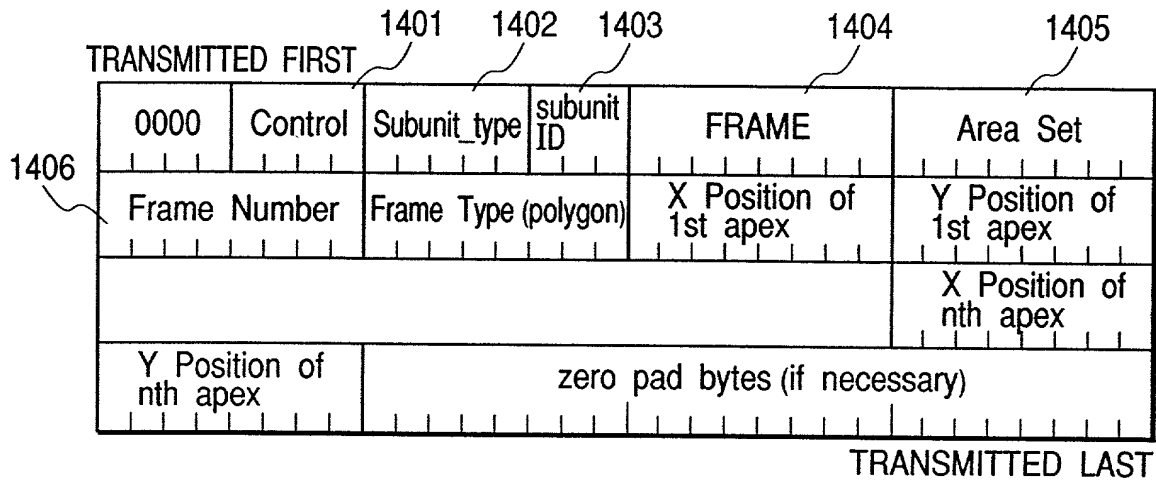
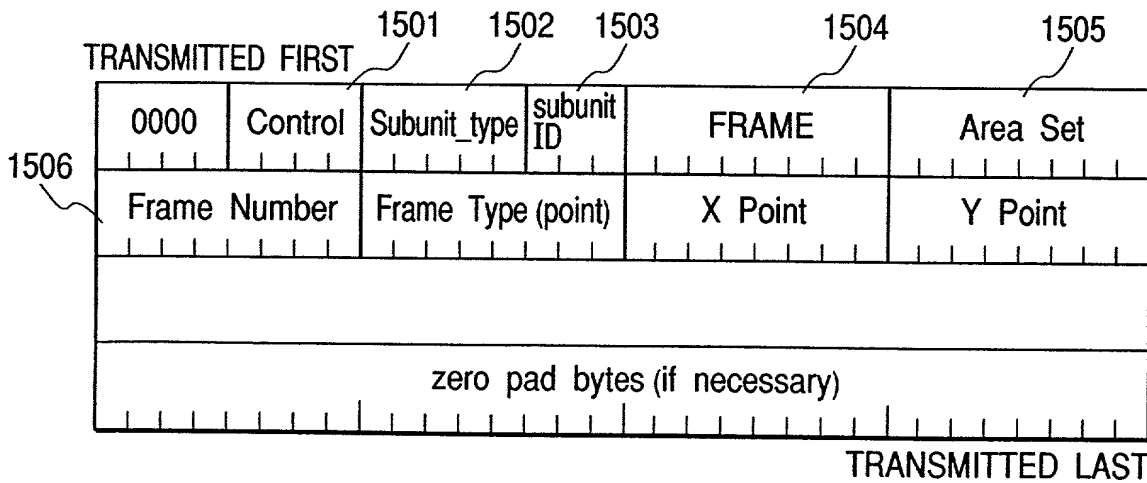
FIG. 14**FIG. 15**

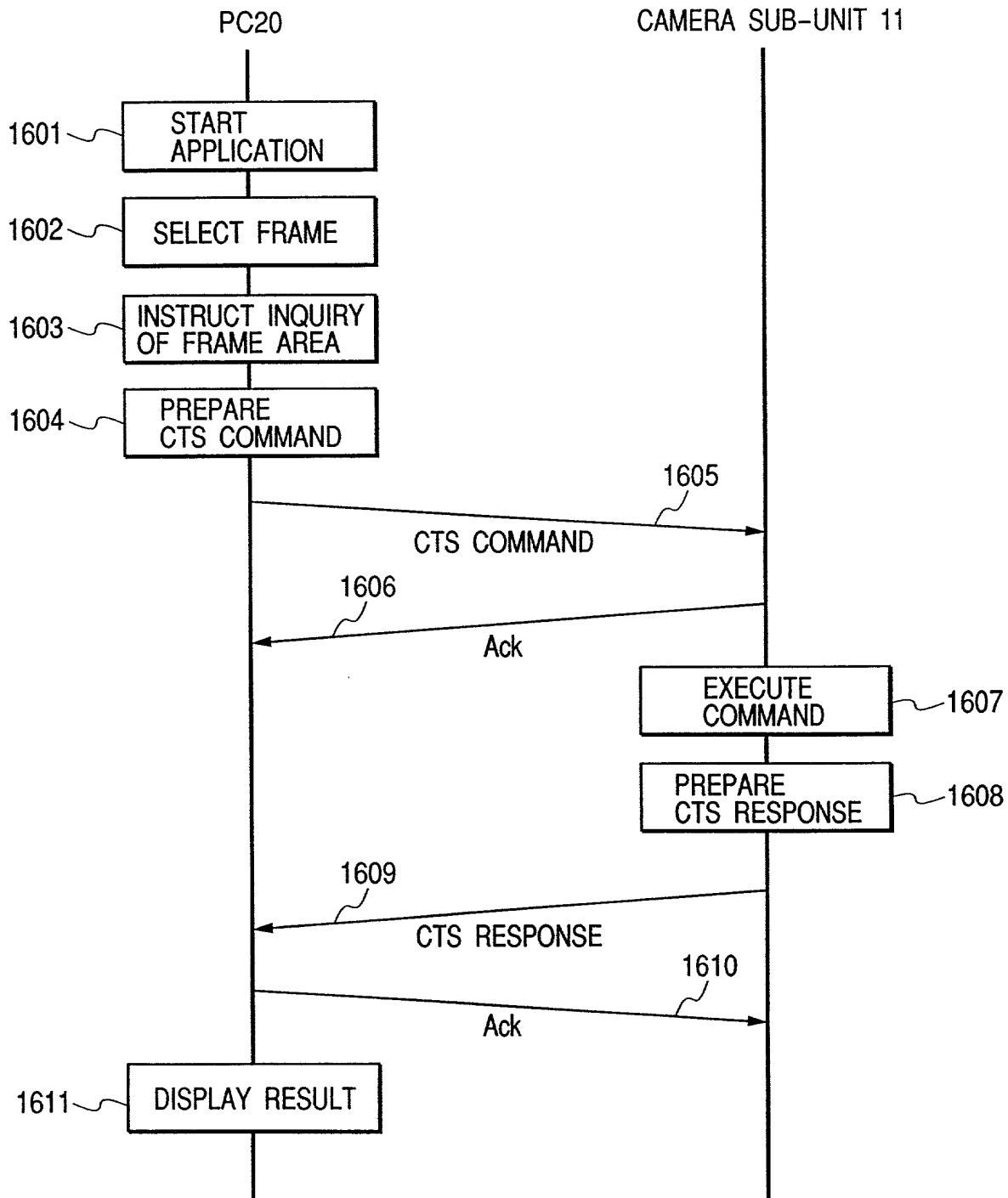
FIG. 16

FIG. 17

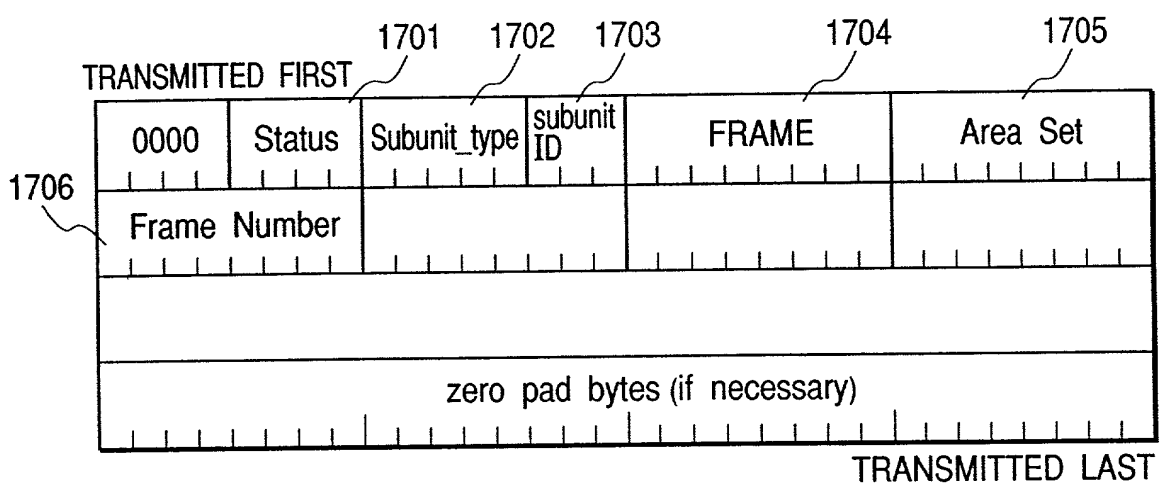


FIG. 19

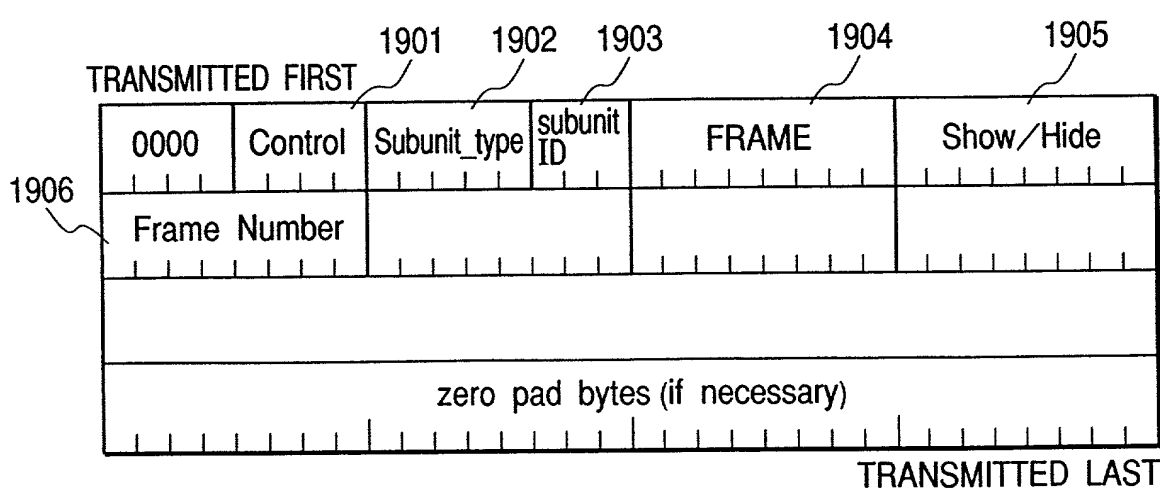


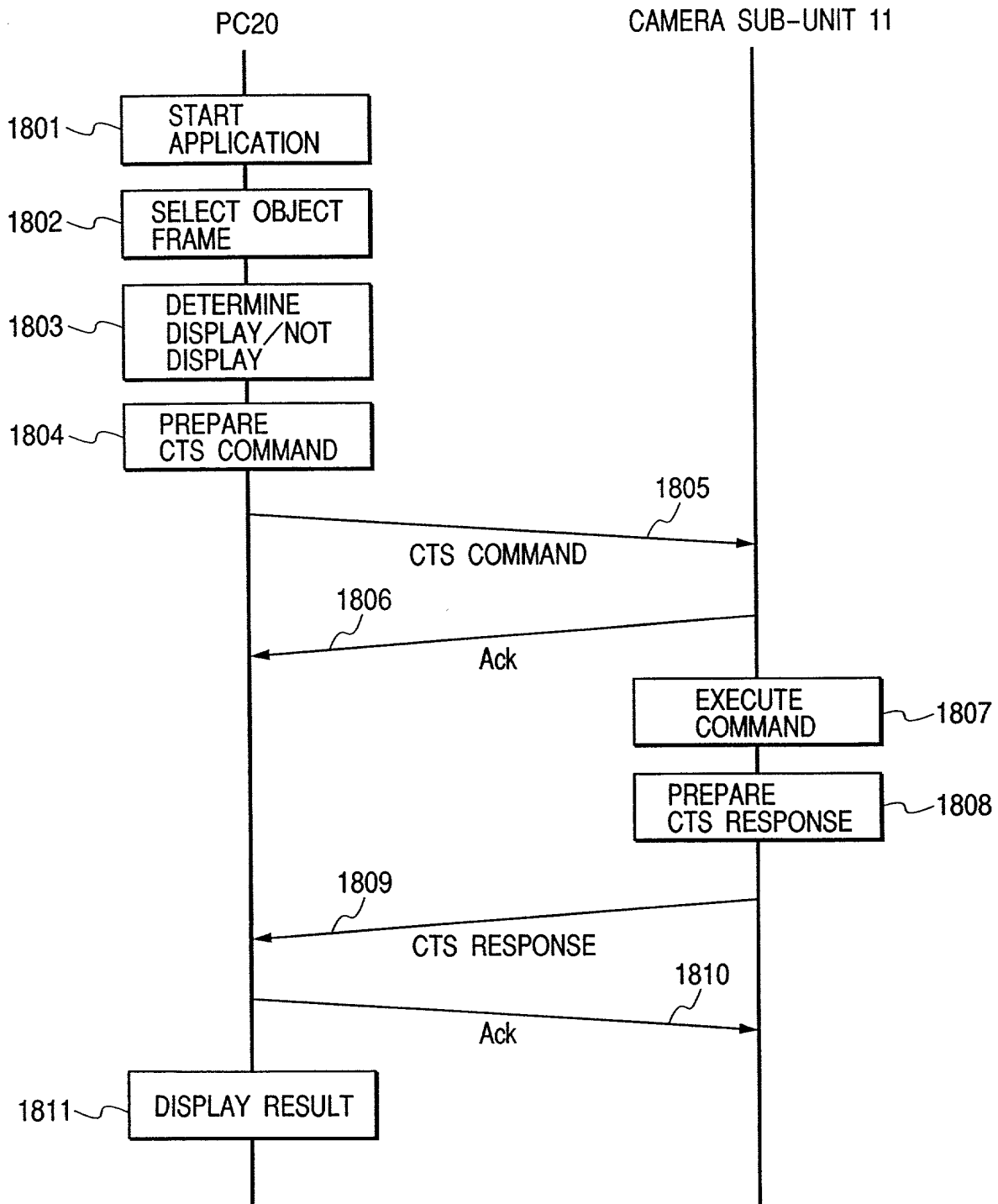
FIG. 18

FIG. 20

FIG. 20

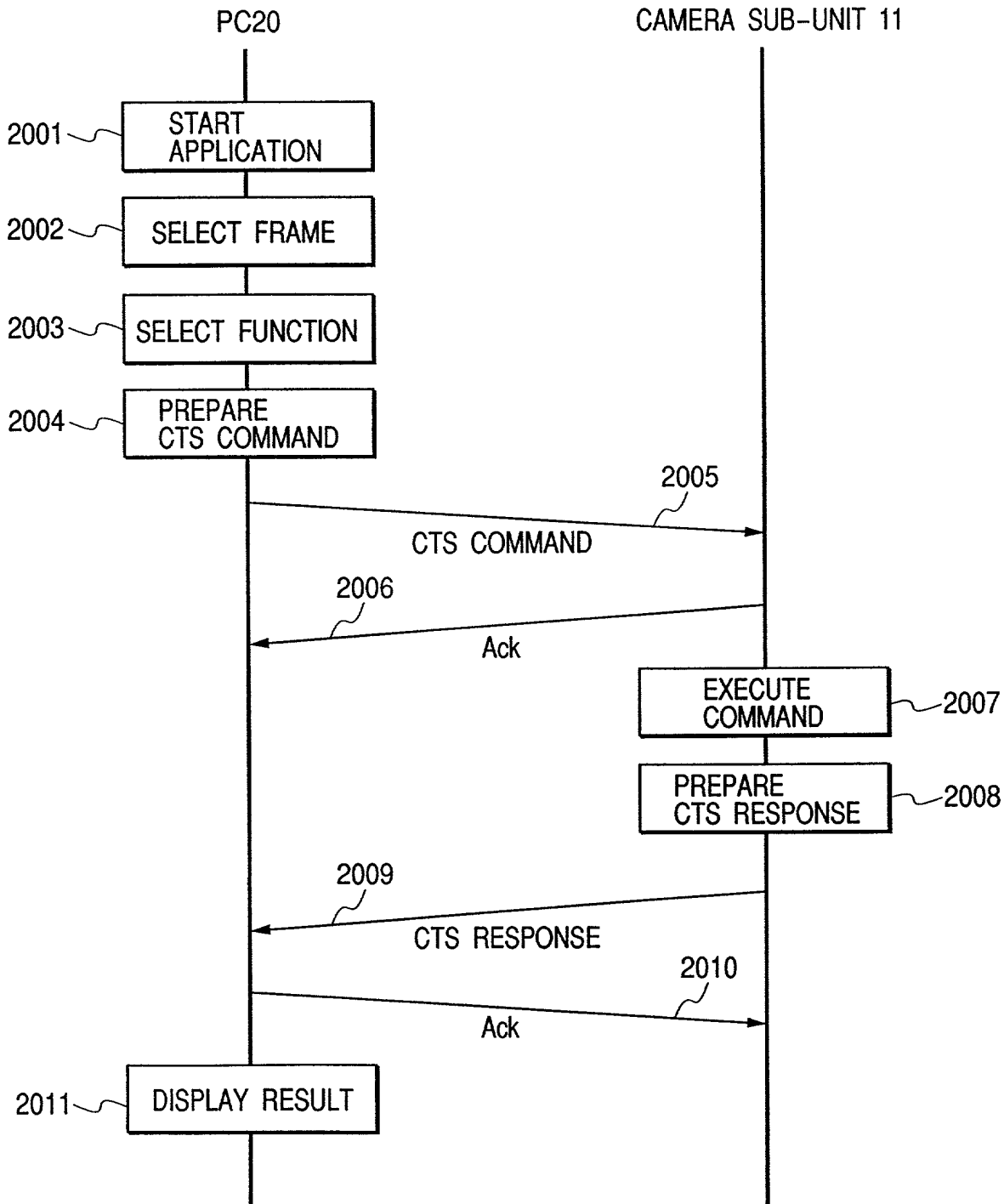


FIG. 21

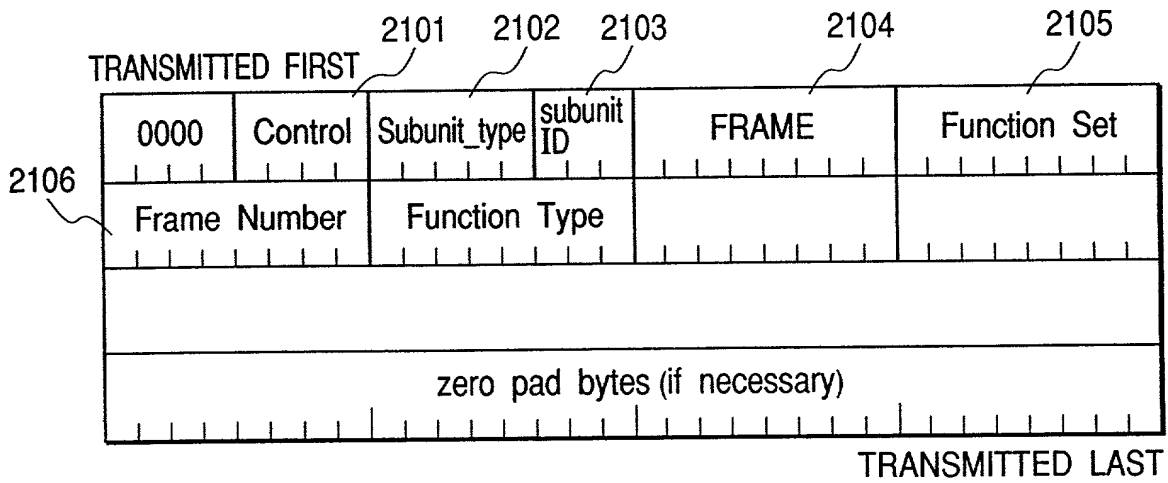


FIG. 22

FUNCTION TYPE	PROCESS CONTENT
AUTO FOCUS	EXECUTE AUTOMATIC FOCUS
AUTO EXPOSURE	EXECUTE AUTOMATIC EXPOSURE
WHITE BALANCE	EXECUTE WHITE BALANCE SETTING
ZOOM	EXECUTE DIGITAL ZOOM

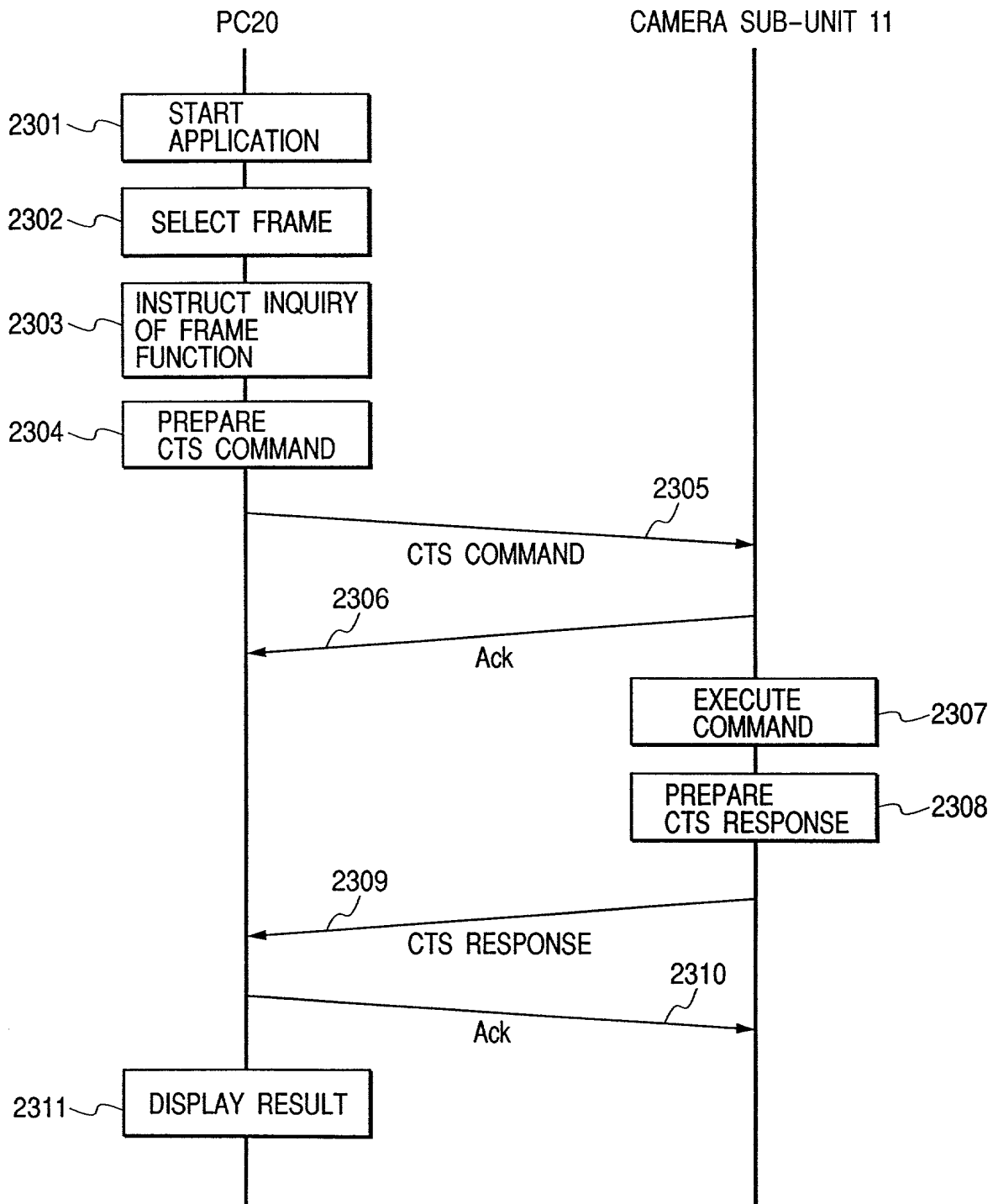
FIG. 23

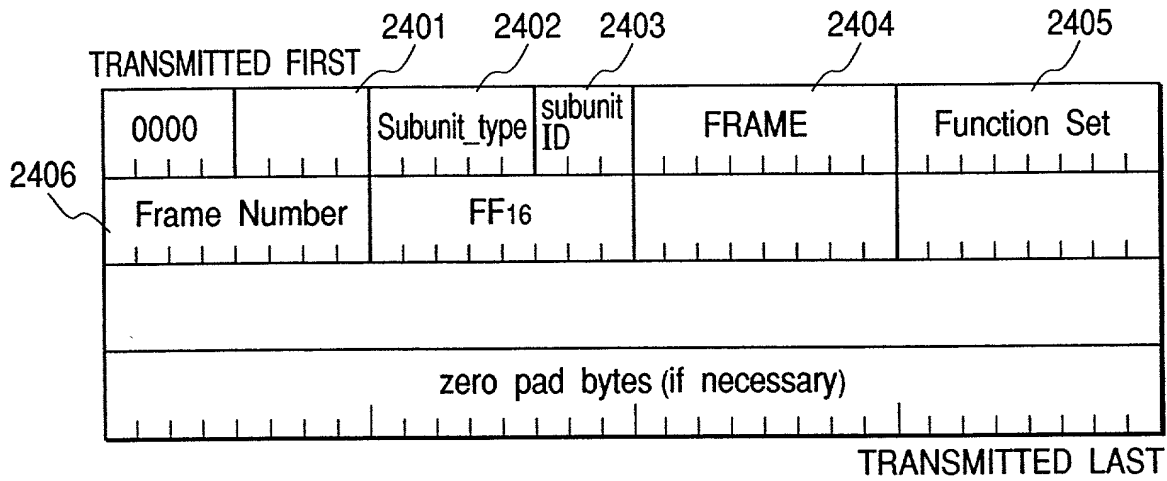
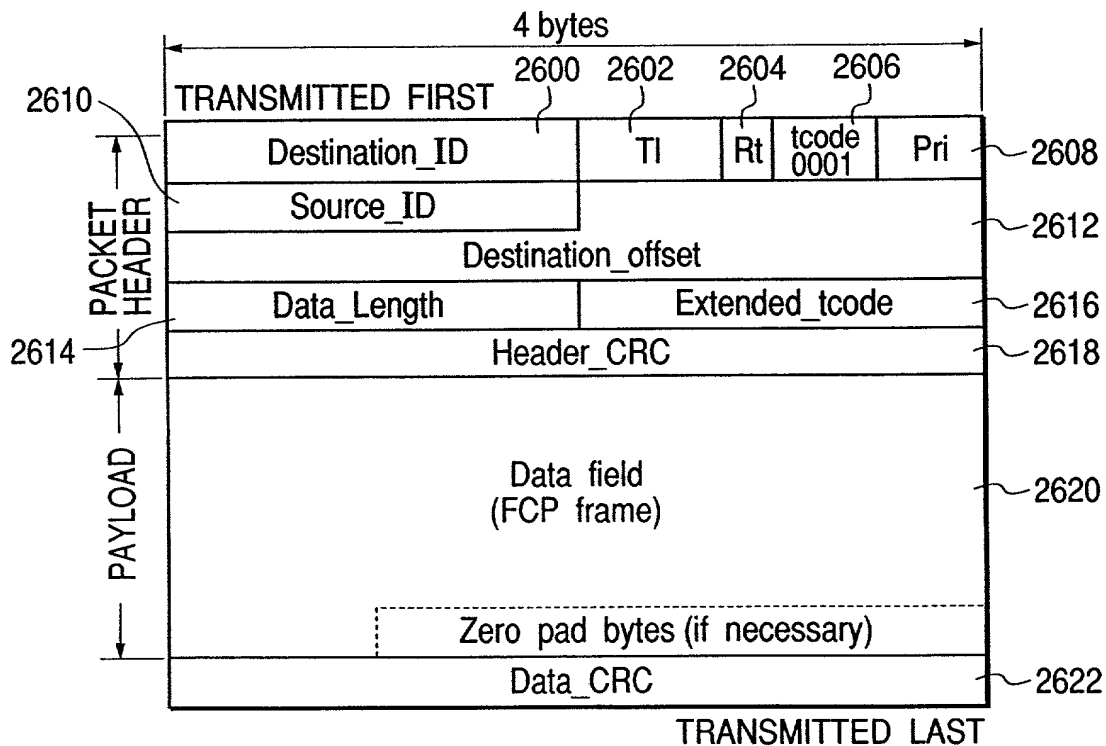
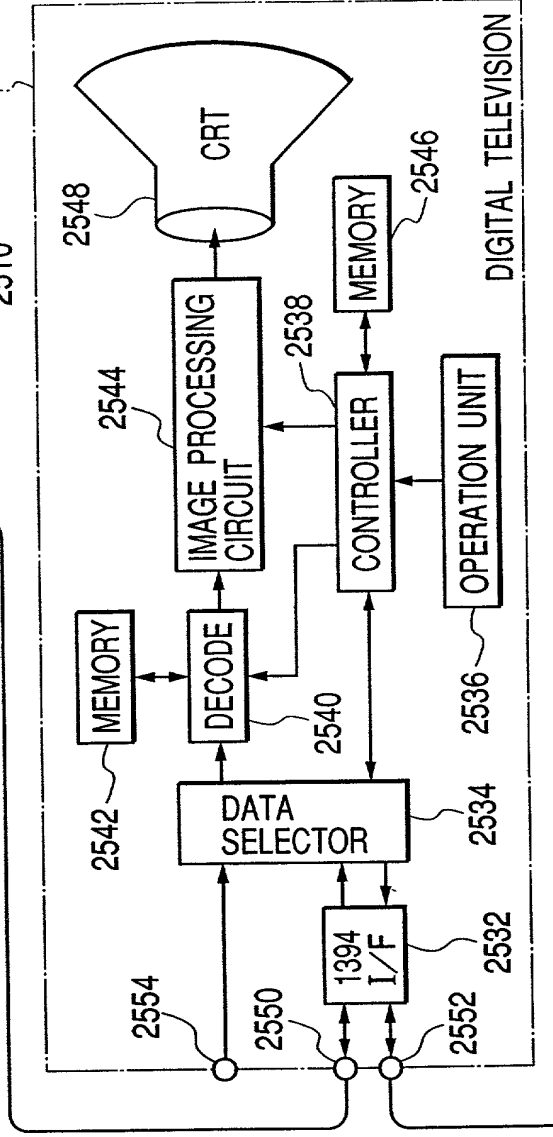
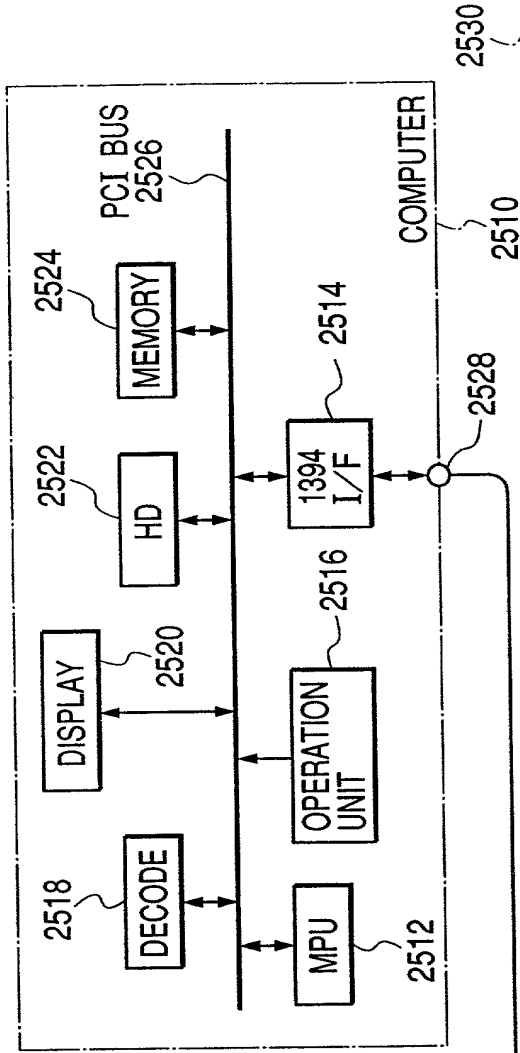
FIG. 24**FIG. 26**

FIG. 25

FIG. 25A
FIG. 25B

FIG. 25A



TO FIG. 25B

FIG. 25B

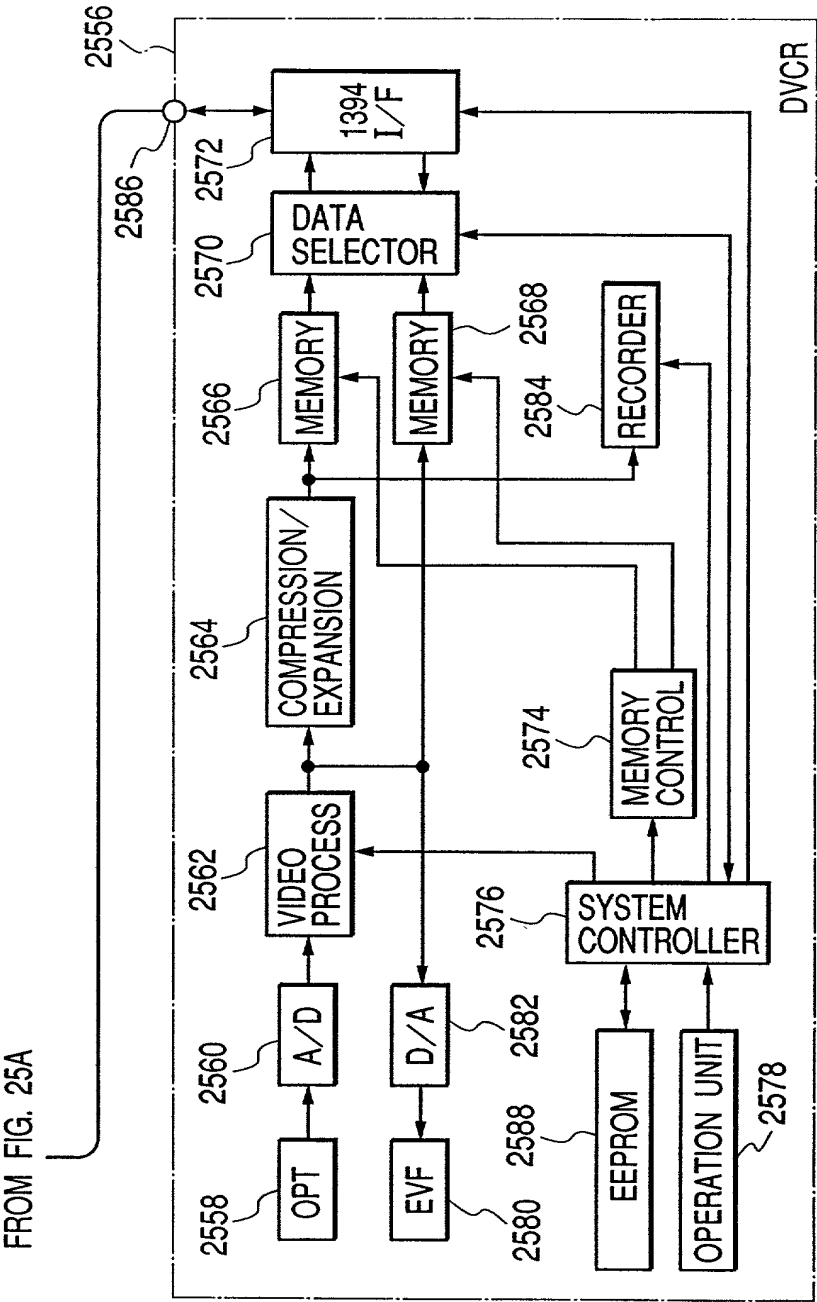


FIG. 27A

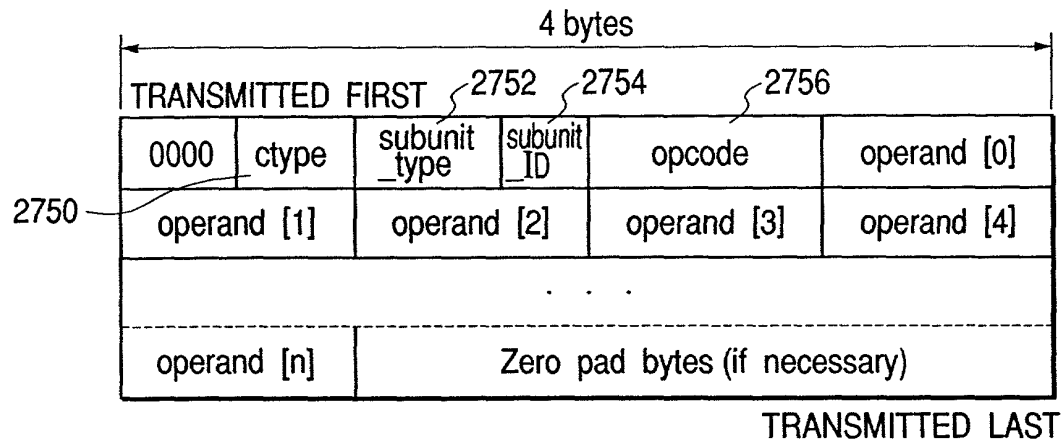


FIG. 27B

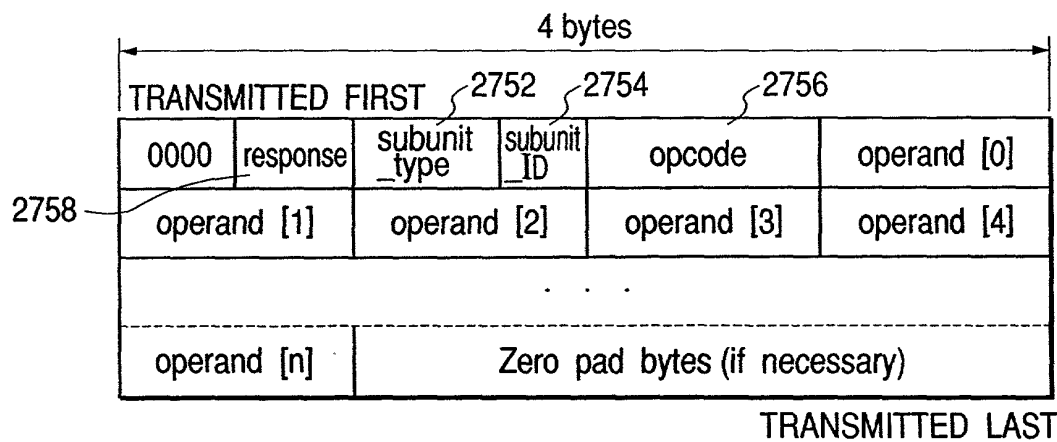


FIG. 28

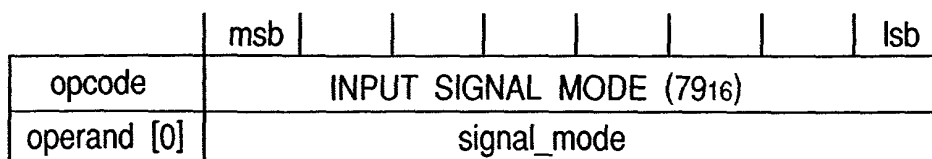


FIG. 29

2970

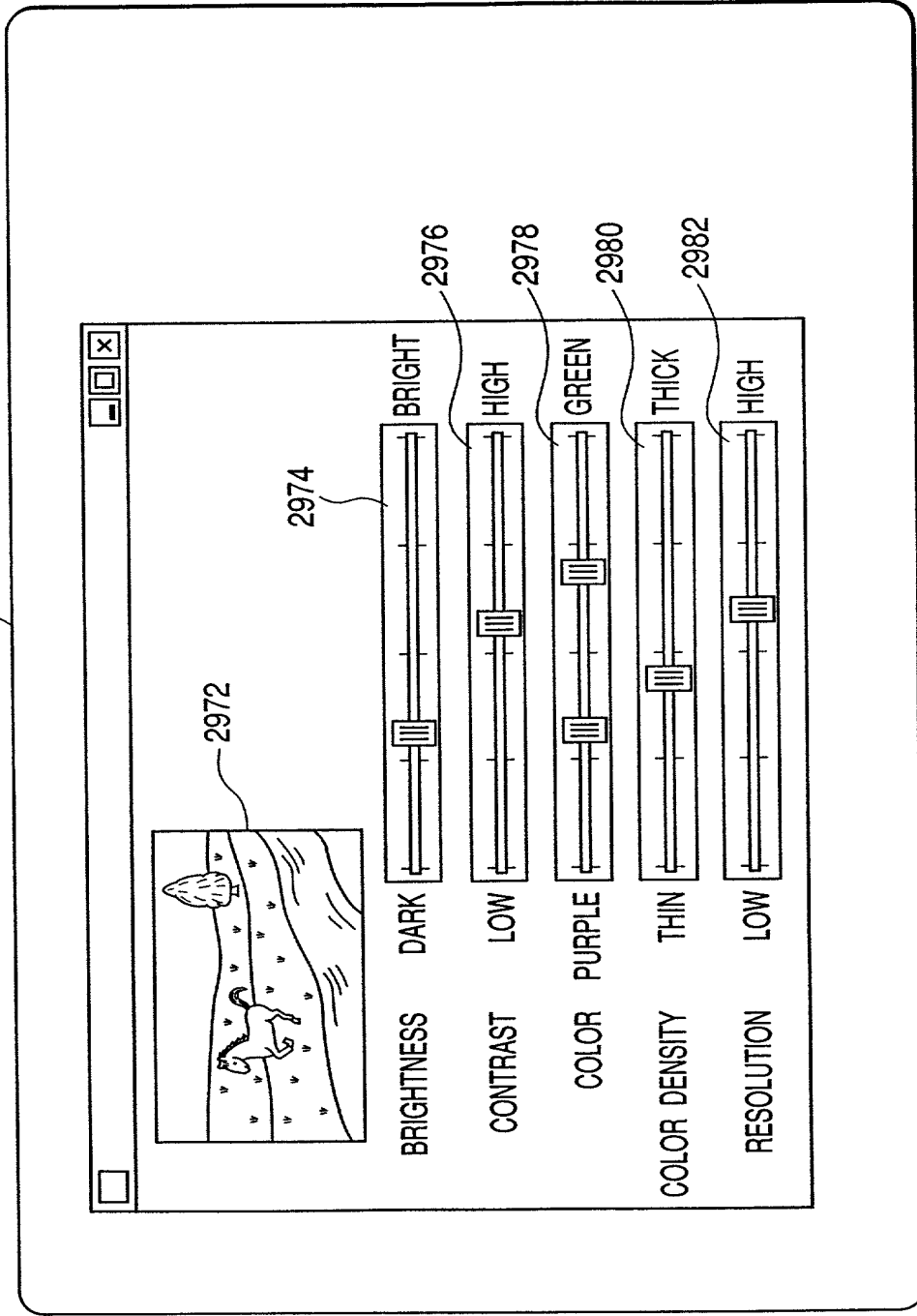


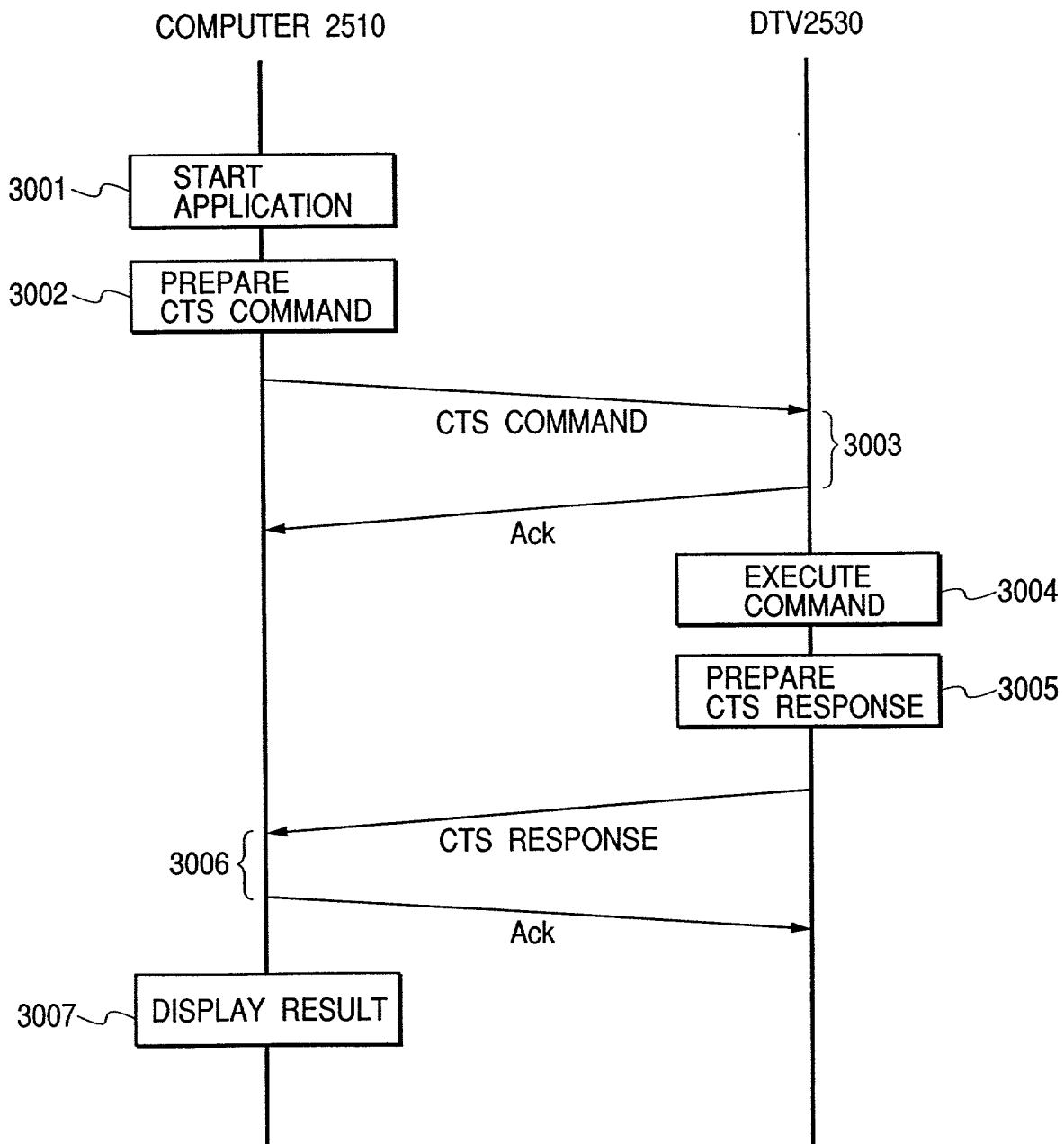
FIG. 30

FIG. 31

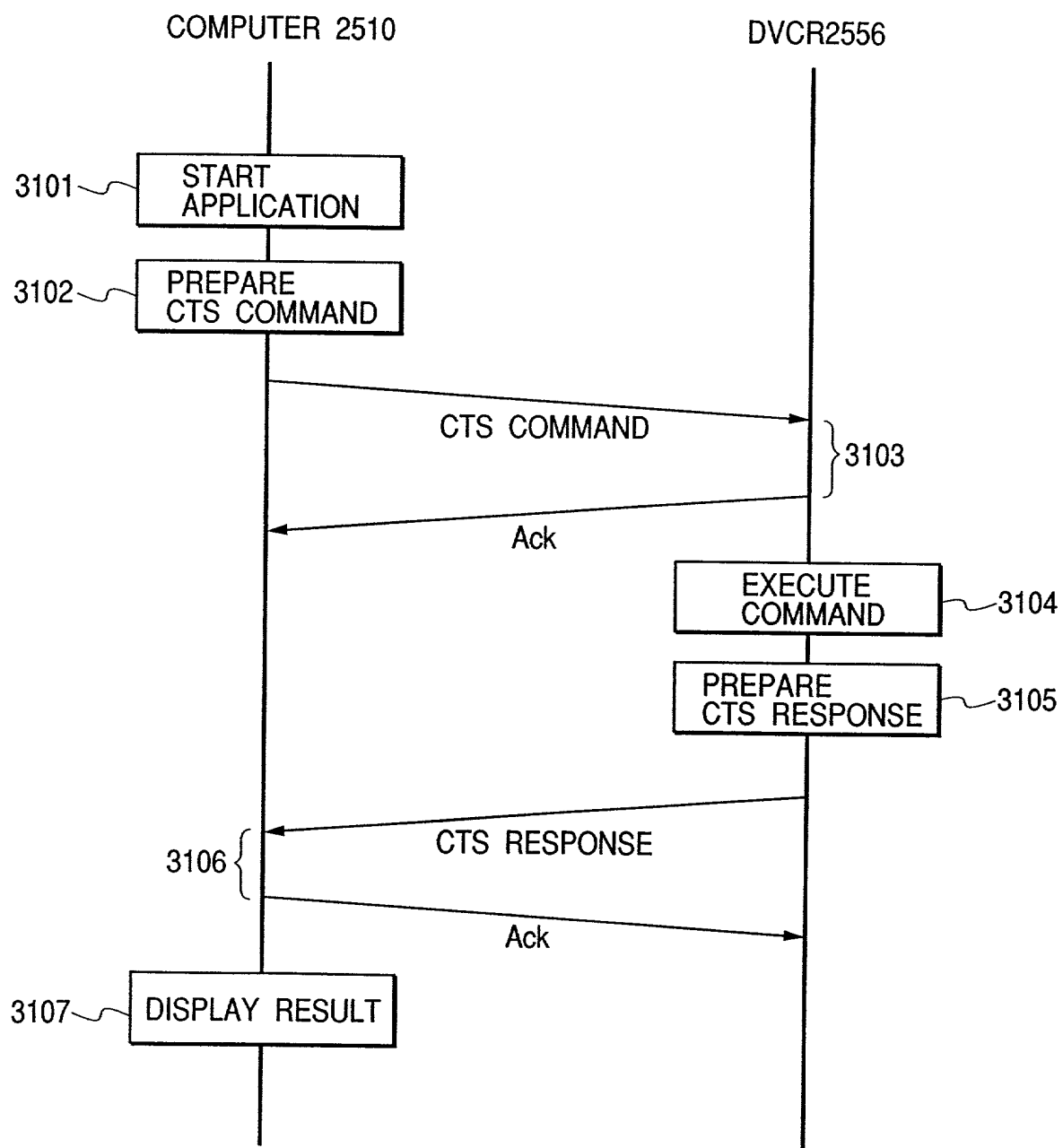
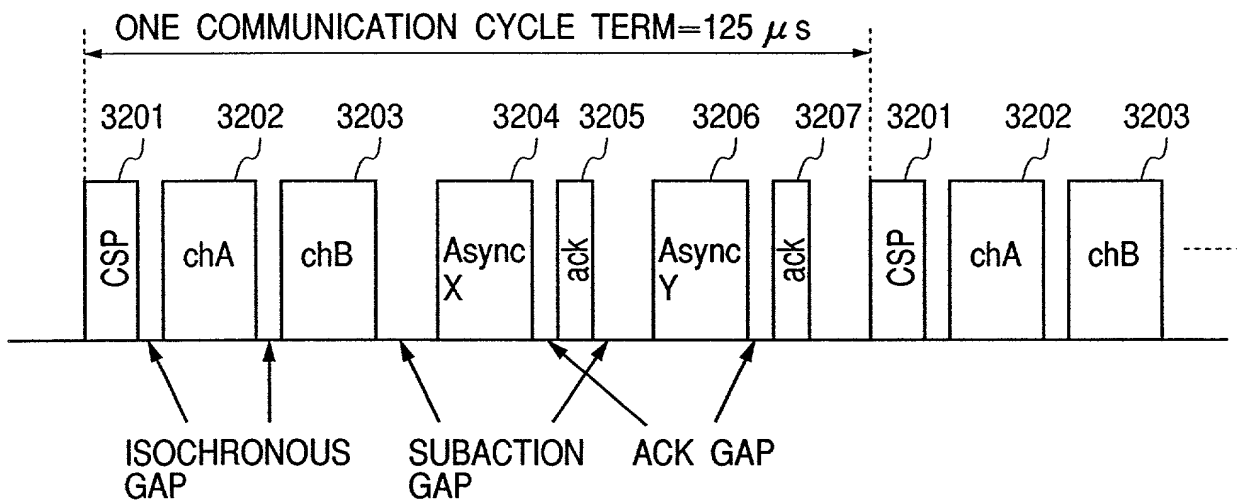


FIG. 32

COMBINED DECLARATION AND POWER OF ATTORNEY
FOR PATENT APPLICATION

(Page 1)

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe I am an original, first and joint inventor of the subject matter which is claimed and for which a patent is sought on the invention entitled DATA COMMUNICATION SYSTEM, DATA COMMUNICATION CONTROL METHOD AND ELECTRONIC APPARATUS,

the specification of which ☒ is attached hereto ☐ was filed on _____ as United States Application No. or PCT International Application No. _____ and was amended on _____ (if applicable).

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to patentability as defined in 37 CFR §1.56.

I hereby claim foreign priority benefits under 35 U.S.C. §119(a)-(d) or §365(b), of any foreign application(s) for patent or inventor's certificate, or § 365(a) of any PCT international application which designates at least one country other than the United States, listed below and have also identified below any foreign application for patent or inventor's certificate, or PCT international application having a filing date before that of the application on which priority is claimed:

<u>Country</u>	<u>Application No.</u>	<u>Filed (Day/Mo./Yr.)</u>	<u>(Yes/No)</u> <u>Priority Claimed</u>
Japan	10-212758	28 July 1998	Yes
Japan	10-311331	30 October 1998	Yes

I hereby claim the benefit under 35 U.S.C. § 120 of any United States application(s), or § 365(c) of any PCT international application designating the United States, listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States or PCT international application in the manner provided by the first paragraph of 35 U.S.C. § 112, I acknowledge the duty to disclose information which is material to patentability as defined in 37 C.F.R. § 1.56 which became available between the filing date of the prior application and the national or PCT international filing date of this application.

<u>Application No.</u>	<u>Filed (Day/Mo./Yr.)</u>	<u>Status (Patented, Pending, Abandoned)</u>
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I hereby appoint the practitioners associated with the firm and Customer Number provided below to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith, and direct that all correspondence be addressed to the address associated with that Customer Number:

FITZPATRICK, CELLA, HARPER & SCINTO
Customer Number: 05514

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

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